

## Trilogy

Linear Motors and Positioners


## $\triangle$ <br> WARNING - USER RESPONSIBILITY

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## I-FORCE Ironless linear motors



Parker Trilogy's I-Force ironless linear motors offer high forces and rapid accelerations in a compact package. With forces ranging from $5.5 \mathrm{lbf}(24.5 \mathrm{~N})-197.5 \mathrm{lbf}(878.6 \mathrm{~N})$ continuous up to $5.5 \mathrm{lbf}(24.5 \mathrm{~N})$ - (883 lbf (3928 N) peak, the I-Force family offers a superior combination of performance and size.

The I-Force patented I-beam shape with its overlapping windings allows for a higher power density in a smaller motor, improved heat removal, and added structural stiffness. In addition, the ironless (or air core) linear motor design has no attractive force toward the magnets. This allows for easy installation and zero cogging during motion.

Ultra high-flex cables come standard with I-Force motors. In addition, we offer modular magnet tracks for unrestricted travel length. Incredibly smooth motion, high precision and high force density make the I-Force linear motors an ideal solution for your demanding positioning requirements.

## Overlapping Windings:

- Increased force density
- Improved heat dissipation
- Lower temperature rise
- Smaller, less expensive motor

No attractive force toward the magnets:

- Easier/Safer assembly and handling, smoother travel (no cogging)

Uses thermally conductive epoxy together with the windings
(Patented RE34674):

- Better heat dissipation

Vacuum encapsulation process:

- Allows motors to be used in high-vacuum environments (Rated at $10^{\wedge}-6$ torr, currently used in $10^{\wedge}-7$ torr applications)


## Modular magnet track:

- Unrestricted travel length

Embedded overtemp thermostat or optional thermistor:

- Protects windings against overheating

Ultra high-flex cables:

- Longer cable life, good for millions of cycles

I-Force Ironless Linear Motors

## 110 Specifications



## IFORCE

- Ironless motor, patented, RE34674
- Cross-section: 2.05 "H ( 50 mm ) x 0.82 "W ( 21 mm )
- Peak forces in two sizes to 45lbs (200N), continuous forces to 10lbs (44N)
- Precision ground 3-piece track (110 model)
- Two lengths of modular magnet tracks allow unlimited length of travel
- Single-piece magnet tracks to 36 " length
- Prealigned imbedded digital Hall effect devices
- Internal thermal cutout switch protects coil

PERFORMANCE

| MOTOR MODEL |  | $\mathbf{1 1 0 - 1}$ | $\mathbf{1 1 0 - 2}$ |
| :---: | :---: | :---: | :---: |
| Peak Force | N | 108.5 | 202.5 |
|  | Ib | 24.4 | 45.5 |
| Continuous Force | N | 24.5 | 10.4 |
| Peak Power | Ib | 5.5 | 1641 |
| Continuous Power | W | 938 | 82 |

ELECTRICAL

| MOTOR MODEL |  | 110-1 |  |  | 110-2 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| WIRING TYPE | UNITS | S-Series | P-Parallel | T-Triple | S-Series | P-Parallel | T-Triple |
| Peak Current | $A^{\text {pk sine }}$ | 15.9 | 31.8 | 47.7 | 14.8 | 29.6 | 44.4 |
|  | (RMS) | 11.2 | 22.5 | 33.7 | 10.4 | 20.9 | 31.4 |
| Continuous Current | $A^{\text {pk sine }}$ | 3.6 | 7.2 | 10.8 | 3.3 | 6.6 | 9.9 |
|  | (RMS) | 2.5 | 5.1 | 7.6 | 2.3 | 4.7 | 7.0 |
| Force Constant | N/A peak | 6.8 | 3.4 | 2.3 | 13.7 | 6.8 | 4.6 |
|  | lb/A peak | 1.5 | 0.8 | 0.5 | 3.1 | 1.5 | 1.0 |
| Back EMF | V/m/s | 7.9 | 3.9 | 2.6 | 15.7 | 7.9 | 5.2 |
|  | V/in/s | 0.20 | 0.10 | 0.07 | 0.40 | 0.20 | 0.13 |
| Resistance $25^{\circ} \mathrm{C}$, phase to phase | ohms | 3.8 | 1.0 | 0.4 | 7.6 | 1.9 | 1.0 |
| Inductance, phase to phase | mH | 1.0 | 0.3 | 0.1 | 2.0 | 0.5 | 0.2 |
| Electrical Time Constant | ms | 0.3 | 0.3 | 0.3 | 0.3 | 0.3 | 0.3 |
| Motor Constant | N/W | 3.56 | 3.56 | 3.56 | 5.02 | 5.02 | 5.02 |
|  | lb/W | 0.80 | 0.80 | 0.80 | 1.13 | 1.13 | 1.13 |
| Max Terminal Voltage | VDC | 330 | 330 | 330 | 330 | 330 | 330 |
| THERMAL |  |  |  |  |  |  |  |
| MOTOR MODEL |  |  | 110-1 |  | 110-2 |  |  |
| Thermal Resistance Wind-Amb | degC / W |  | 1.59 |  | 0.92 |  |  |
| Thermal Time Constant | min |  | 3.2 |  | 3.2 |  |  |
| Maximum Winding Temperature | ${ }^{\circ} \mathrm{C}$ |  | 100 |  | 100 |  |  |
| MECHANICAL |  |  |  |  |  |  |  |
| MOTOR MODEL |  |  | 110-1 |  | 110-2 |  |  |
| Coil Weight | kg |  | 0.12 |  | 0.22 |  |  |
|  | lb |  | 0.27 |  | 0.48 |  |  |
| Coil Length | mm |  | 81.3 |  | 142.2 |  |  |
|  | in |  | 3.20 |  | 5.60 |  |  |
| Attractive Force | N |  | 0 |  | 0 |  |  |
|  | lbf |  | 0 |  | 0 |  |  |
| Electrical Cycle Length | mm |  | 60.96 |  | 60.96 |  |  |
|  | in |  | 2.40 |  | 2.40 |  |  |


(A) ENGLISH TOP MOUNTING


| COIL SIZE (inches) | L | N | A | B | C |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $110-1 \mathrm{~A}$ | 3.20 | 4 | 0.50 | 2.70 | --- |
| $110-2 \mathrm{~A}$ | 5.60 | 6 | 0.50 | 2.80 | 5.10 |

(M) METRIC TOP MOUNTING


| COIL SIZE (mm) | L | N | A | B | C |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $110-1 M$ | 81.3 | 4 | 12.7 | 68.6 | --- |
| $110-2 M$ | 142.2 | 6 | 12.7 | 71.1 | 129.5 |

(B) ENGLISH SIDE MOUNTING


| COIL SIZE (inches) | L | N | A | B |
| :---: | :---: | :---: | :---: | :---: |
| $110-1 B$ | 3.20 | 2 | 0.80 | 2.40 |
| $110-2 B$ | 5.60 | 2 | 0.80 | 4.80 |

(N) METRIC SIDE MOUNTING


| COIL SIZE $(\mathbf{m m})$ | L | N | A | B |
| :---: | :---: | :---: | :---: | :---: |
| $110-1 \mathrm{~N}$ | 81.3 | 2 | 20.3 | 60.9 |
| $110-2 \mathrm{~N}$ | 142.2 | 2 | 20.3 | 121.9 |


| LENGTH <br> ln lnches | MODULAR TRACK <br> LENGTH <br> $\mathbf{n ~ m m}$ | QUANTITY <br> $\mathbf{1 1 0 0 7 M}$ <br> $\mathbf{1 1 5 0 7 M}$ | QUANTITY <br> $\mathbf{1 1 0 0 9 M}$ <br> $\mathbf{1 1 5 0 9 M}$ |
| :---: | :---: | :---: | :---: |
| 7.2 | 182.9 | 1 | 0 |
| 9.6 | 243.8 | 0 | 1 |
| 12.0 | 304.8 | 0 | 0 |
| 14.4 | 365.8 | 2 | 0 |
| 16.8 | 426.7 | 1 | 1 |
| 19.2 | 487.7 | 0 | 2 |
| 21.6 | 548.6 | 3 | 0 |
| 24.0 | 609.6 | 2 | 1 |
| 26.4 | 670.6 | 1 | 2 |
| 28.8 | 731.5 | 0 | 3 |
| 31.2 | 792.5 | 3 | 1 |
| 33.6 | 853.4 | 2 | 2 |
| 36.0 | 914.4 | 1 | 3 |
| 38.4 | 975.4 | 0 | 4 |
| 40.8 | 1036.3 | 3 | 2 |
| 43.2 | 1097.3 | 2 | 3 |
| 45.6 | 1158.2 | 1 | 4 |
| 48.0 | 1219.2 | 0 | 5 |
| 50.4 | 1280.2 | 3 | 3 |
| 52.8 | 1341.1 | 2 | 4 |
| 55.2 | 1402.1 | 1 | 5 |
| 57.6 | 1463.0 | 0 | 6 |
| 60.0 | 1524.0 | 3 | 4 |
| 62.4 | 1585.0 | 2 | 5 |
| 64.8 | 1645.9 | 1 | 6 |
| 67.2 | 1706.9 | 0 | 7 |
| 69.6 | 1767.8 | 3 | 5 |
| 72.0 | 1828.8 | 2 | 6 |



| 10xxS |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| P/N 110xx | S | L (in) | L (mm) | A | mm | N |
| 11008 | S | 8.4 | 205.8 | 0.20 | 5.08 | 3 |
| 11009 | S | 9.6 | 235.2 | 0.80 | 20.32 | 3 |
| 11010 | S | 10.8 | 264.6 | 1.40 | 35.56 | 3 |
| 11012 | S | 12.0 | 294.0 | 2.00 | 50.80 | 3 |
| 11013 | S | 13.2 | 323.4 | 2.60 | 66.04 | 3 |
| 11014 | S | 14.4 | 352.8 | 3.20 | 81.28 | 3 |
| 11015 | S | 15.6 | 382.2 | 3.80 | 96.52 | 3 |
| 11016 | S | 16.8 | 411.6 | 0.40 | 10.16 | 5 |
| 11018 | S | 18.0 | 441.0 | 1.00 | 25.40 | 5 |
| 11019 | S | 19.2 | 470.4 | 1.60 | 40.64 | 5 |
| 11020 | S | 20.4 | 499.8 | 2.20 | 55.88 | 5 |
| 11021 | S | 21.6 | 529.2 | 2.80 | 71.12 | 5 |
| 11022 | S | 22.8 | 558.6 | 3.40 | 86.36 | 5 |
| 11024 | S | 24.0 | 588.0 | 4.00 | 101.60 | 5 |
| 11025 | S | 25.2 | 617.4 | 0.60 | 15.24 | 7 |
| 11026 | S | 26.4 | 646.8 | 1.20 | 30.48 | 7 |
| 11027 | S | 27.6 | 676.2 | 1.80 | 45.72 | 7 |
| 11028 | S | 28.8 | 705.6 | 2.40 | 60.96 | 7 |
| 11030 | S | 30.0 | 735.0 | 3.00 | 76.20 | 7 |
| 11031 | S | 31.2 | 764.4 | 3.60 | 91.44 | 7 |
| 11032 | S | 32.4 | 793.8 | 0.20 | 5.08 | 9 |
| 11033 | S | 33.6 | 823.2 | 0.80 | 20.32 | 9 |
| 11034 | S | 34.8 | 852.6 | 1.40 | 35.56 | 9 |
| 11036 | S | 36.0 | 882.0 | 2.00 | 50.80 | 9 |


| SINGLE PIECE 110xxM |  |  |  |
| ---: | ---: | ---: | ---: |
| P/N 110xx M | L(in) | L(mm) | N |
| 11002 M | 2.4 | 60.96 | 1 |
| 11004 M | 4.8 | 121.92 | 2 |
| 11007 M | 7.2 | 182.88 | 3 |
| 11009 M | 9.6 | 243.84 | 4 |
| 11012 M | 12.0 | 304.80 | 5 |
| 11014 M | 14.4 | 365.76 | 6 |
| 11016 M | 16.8 | 426.72 | 7 |
| 11019 M | 19.2 | 487.68 | 8 |
| 11021 M | 21.6 | 548.64 | 9 |
| 11024 M | 24.0 | 609.60 | 10 |
| 11026 M | 26.4 | 670.56 | 11 |
| 11028 M | 28.8 | 731.52 | 12 |
| 11031 M | 31.2 | 792.48 | 13 |
| 11033 M | 33.6 | 853.44 | 14 |
| 11036 M | 36.0 | 914.40 | 15 |



## NOTES

1. Peak force and current based on $5 \%$ duty cycle and one second duration.
2. Continuous force and current based on coil winding temperature maintained at $100^{\circ} \mathrm{C}$
3. Force constant is peak of resistive force produced by 1.0 amp thru one motor lead and 0.5 amps thru other two leads. Also, Back EMF (V/in/sec) * $7.665=$ Force constant (ib/amp).
4. Motor resistance measured between any two motor leads with motor connected in Delta winding at $25^{\circ} \mathrm{C}$.

For temperature at $100^{\circ} \mathrm{C}$, multiply resistance by $1.295\left(75^{\circ} \mathrm{C}\right.$ rise * $0.393 \% /{ }^{\circ} \mathrm{C}$ )
5. Back EMF measured between any two motor leads while moving at constant velocity. Value is amplitude or 0-Peak of sine wave produced.
6. Motor inductance measured using 1 Kz with the motor in the magnetic field.
7. Electrical Time Constant is time it takes for motor value to reach $63 \%$ of its final current after a step change in voltage.


## WD3



Thermostat(NC)
Opens at $90^{\circ} \mathrm{C}$

8. Thermal Time Constant is time it takes for motor temperature to reach $63 \%$ of its final value after a step change in power.
9. Thermal Resistance is the number of degrees (Celsius) of temperature rise in the winding per watt of power dissipated. Determined experimentally.
10. Motor Constant is a measure of efficiency. Calculated by dividing the force constant by the square root of the motor resistance at maximum operating temperature.
11. Electrical Cycle Length is distance coil must travel to complete $360^{\circ}$ electrical cycle.
12. Use TIPS sizing software for the most accurate estimate of coil temperature for a particular motion profile.
13. Motors available with nickel plating or black epoxy coating on magnets. Track part number modified with -N or -B at end. Must be specified at time of order.

## TFORCE

- Ironless motor, patented, RE34674
- Cross-section: 2.25 "H ( 57.1 mm ) x 1.25 "W ( 31.7 mm )
- Peak forces in four sizes to 110lbs (494), continuous forces to 24.8lb (104.5N)
- Precision ground 3-piece track ( 210 model)
- Two lengths of modular magnet tracks allow unlimited length of travel
- Prealigned imbedded digital HEDs, also available in separate cable from motor leads
- Internal air cooling manifold standard
- Internal thermal cutout switch protects coil

PERFORMANCE

| MOTOR MODEL |  | $\mathbf{2 1 0 - 1}$ | $\mathbf{2 1 0 - 2}$ | $\mathbf{2 1 0 - 3}$ | $\mathbf{2 1 0 - 4}$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Peak Force | N | 137.0 | 255.8 | 375.0 | 494.2 |
|  | Ib | 30.8 | 57.5 | 84.3 | 111.1 |
| Continuous Force | N | 30.7 | 57.4 | 84.1 | 110.3 |
| Peak Power | Ib | 6.9 | 12.9 | 18.9 | 24.8 |
| Continuous Power | W | 905 | 1583 | 2261 | 140 |

ELECTRICAL

| MOTOR MODEL |  | 210-1 |  |  | 210-2 |  |  | 210-3 |  |  | 210-4 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| WIRING TYPE | UNITS | S-Series | P-Parallel | T-Triple | S-Series | P-Parallel | T-Triple | S-Series | P-Parallel | T-Triple | S-Series | P-Parallel | T-Triple |
| Peak Current | $A^{\text {pk sine }}$ | 12.6 | 25.2 | 37.8 | 11.8 | 23.6 | 35.4 | 11.5 | 23 | 34.5 | 11.3 | 22.6 | 33.9 |
|  | (RMS) | 8.9 | 17.8 | 26.7 | 8.3 | 16.7 | 25.0 | 8.1 | 16.3 | 24.4 | 8.0 | 16.0 | 23.9 |
| Continuous Current | $A^{\text {pk sine }}$ | 2.8 | 5.6 | 8.4 | 2.6 | 5.2 | 7.8 | 2.6 | 5.2 | 7.8 | 2.5 | 5.0 | 7.5 |
|  | (RMS) | 1.9 | 3.9 | 5.9 | 1.8 | 3.7 | 5.5 | 1.8 | 3.7 | 5.5 | 1.8 | 3.5 | 5.3 |
| Force Constant | N/A peak | 10.9 | 5.4 | 3.6 | 21.8 | 10.9 | 7.3 | 32.7 | 16.4 | 10.9 | 43.6 | 21.8 | 14.5 |
|  | lb/A peak | 2.5 | 1.2 | 0.8 | 4.9 | 2.5 | 1.6 | 7.4 | 3.7 | 2.5 | 9.8 | 4.9 | 3.3 |
| Back EMF | V/m/s | 12.6 | 6.3 | 4.2 | 25.2 | 12.6 | 8.4 | 37.8 | 18.9 | 12.6 | 50.4 | 25.2 | 16.8 |
|  | V/in/s | 0.32 | 0.16 | 0.11 | 0.64 | 0.32 | 0.21 | 0.96 | 0.48 | 0.32 | 1.28 | 0.64 | 0.43 |
| Resistance $25^{\circ} \mathrm{C}$, phase to phase | ohms | 5.9 | 1.5 | 0.7 | 11.8 | 3.0 | 1.3 | 17.7 | 4.4 | 2.0 | 23.6 | 5.9 | 2.6 |
| Inductance, phase to phase | mH | 2.4 | 0.6 | 0.3 | 4.8 | 1.2 | 0.5 | 7.2 | 1.8 | 0.8 | 9.6 | 2.4 | 1.1 |
| Electrical Time Constant | ms | 0.4 | 0.4 | 0.4 | 0.4 | 0.4 | 0.4 | 0.4 | 0.4 | 0.4 | 0.4 | 0.4 | 0.4 |
| Motor Constant | N/W | 4.54 | 4.54 | 4.54 | 6.45 | 6.45 | 6.45 | 7.87 | 7.87 | 7.87 | 9.12 | 9.12 | 9.12 |
|  | lb/W | 1.02 | 1.02 | 1.02 | 1.45 | 1.45 | 1.45 | 1.77 | 1.77 | 1.77 | 2.05 | 2.05 | 2.05 |
| Max Terminal Voltage | VDC | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 |

THERMAL

| MOTOR MODEL | $\mathbf{2 1 0 - 1}$ | $\mathbf{2 1 0 - 2}$ | $\mathbf{2 1 0 - 3}$ | $\mathbf{2 1 0 - 4}$ |  |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Thermal Resistance Wind-Amb | $\operatorname{degC} / \mathrm{W}$ | 1.67 | 0.94 | 0.66 | 0.51 |
| Thermal Time Constant | $\min$ | 4.3 | 4.3 | 4.3 | 4.3 |
| Maximum Winding Temperature | ${ }^{\circ} \mathrm{C}$ | 100 | 100 | 100 | 100 |

MECHANICAL

| MOTOR MODEL |  | 210-1 | 210-2 | 210-3 | 210-4 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Coil Weight | kg | 0.16 | 0.27 | 0.39 | 0.51 |
|  | lb | 0.35 | 0.60 | 0.86 | 1.12 |
| Coil Length | mm | 81.3 | 142.2 | 203.2 | 264.2 |
|  | in | 3.2 | 5.6 | 8.0 | 10.4 |
| Attractive Force | N | 0 | 0 | 0 | 0 |
|  | lbf | 0 | 0 | 0 | 0 |
| Electrical Cycle Length | mm | 60.96 | 60.96 | 60.96 | 60.96 |
|  | in | 2.4 | 2.4 | 2.4 | 2.4 |



Incremental Length: $2.4 \mathrm{in} / 60.96 \mathrm{~mm}$
Minimum Length: $2.4 \mathrm{in} / 60.96 \mathrm{~mm}$
Maximum Length: (For Single Piece) 48in/ 1219.2 mm

Weight/Foot: 5.501bs/ft

Incremental Length: $2.4 \mathrm{in} / 60.96 \mathrm{~mm}$
Minimum Length: $2.4 \mathrm{in} / 60.96 \mathrm{~mm}$
Maximum Length: 48in/1219.2mm
Weight/Foot:
5.50lbs/ft

## Incremental Length:

$1.2 \mathrm{in} / 30.48 \mathrm{~mm}$
Minimum Length:
$8.4 \mathrm{in} / 213.4 \mathrm{~mm}$

## Maximum Length:

 48in/1219.2mmWeight/Foot: 5.50lbs/ft
(A) ENGLISH TOP MOUNTING

(B) ENGLISH SIDE MOUNTING


| COIL SIZE (inches) | L | N | A | B | C |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $210-1 \mathrm{~A}$ | 3.20 | 5 | 0.50 | 1.60 | 2.70 |
| $210-2 \mathrm{~A}$ | 5.60 | 5 | 0.50 | 2.80 | 5.10 |
| $210-3 \mathrm{~A}$ | 8.00 | 5 | 0.50 | 4.00 | 7.50 |
| $210-4 \mathrm{~A}$ | 10.40 | 5 | 0.50 | 5.20 | 9.90 |

(M) METRIC TOP MOUNTING


| COIL SIZE (inches) | L | N | A | B | C |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $210-1 \mathrm{~B}$ | 3.20 | 2 | 1.950 | 2.950 | --- |
| $210-2 \mathrm{~B}$ | 5.60 | 2 | 1.625 | 3.975 | --- |
| $210-3 \mathrm{~B}$ | 8.00 | 3 | 2.438 | 4.000 | 5.562 |
| $210-4 \mathrm{~B}$ | 10.40 | 3 | 2.600 | 5.200 | 7.800 |

(N) METRIC SIDE MOUNTING


| COIL SIZE (mm) | L | N | A | B | C |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $210-1 \mathrm{~N}$ | 81.3 | 2 | 49.5 | 74.9 | --- |
| $210-2 \mathrm{~N}$ | 142.2 | 2 | 41.3 | 101.0 | --- |
| $210-3 \mathrm{~N}$ | 203.2 | 3 | 61.9 | 101.6 | 141.3 |
| $210-4 \mathrm{~N}$ | 264.2 | 3 | 66.0 | 132.1 | 198.1 |

$\left.\begin{array}{cccc}\hline & \text { MODULAR TRACK }\end{array}\right]$
*Please note that 72.0 inches is NOT the maximum length for modular tracks

| 210xxS |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| P/N | 210xx | S | L (in) | L (mm) | A | mm | N |
|  | 21008 | S | 8.4 | 205.8 | 0.20 | 5.08 | 3 |
|  | 21009 | S | 9.6 | 235.2 | 0.80 | 20.32 | 3 |
|  | 21010 | S | 10.8 | 264.6 | 1.40 | 35.56 | 3 |
|  | 21012 | S | 12.0 | 294.0 | 2.00 | 50.80 | 3 |
|  | 21013 | S | 13.2 | 323.4 | 2.60 | 66.04 | 3 |
|  | 21014 | S | 14.4 | 352.8 | 3.20 | 81.28 | 3 |
|  | 21015 | S | 15.6 | 382.2 | 3.80 | 96.52 | 3 |
|  | 21016 | S | 16.8 | 411.6 | 0.40 | 10.16 | 5 |
|  | 21018 | S | 18.0 | 441.0 | 1.00 | 25.40 | 5 |
|  | 21019 | S | 19.2 | 470.4 | 1.60 | 40.64 | 5 |
|  | 21020 | S | 20.4 | 499.8 | 2.20 | 55.88 | 5 |
|  | 21021 | S | 21.6 | 529.2 | 2.80 | 71.12 | 5 |
|  | 21022 | S | 22.8 | 558.6 | 3.40 | 86.36 | 5 |
|  | 21024 | S | 24.0 | 588.0 | 4.00 | 101.60 | 5 |
|  | 21025 | S | 25.2 | 614.4 | 0.60 | 15.24 | 7 |
|  | 21026 | S | 26.4 | 646.8 | 1.20 | 30.48 | 7 |
|  | 21027 | S | 27.6 | 676.2 | 1.80 | 45.72 | 7 |
|  | 21028 | S | 28.8 | 705.6 | 2.40 | 60.96 | 7 |
|  | 21030 | S | 30.0 | 735.0 | 3.00 | 76.20 | 7 |
|  | 21031 | S | 31.2 | 764.4 | 3.60 | 91.44 | 7 |
|  | 21032 | S | 32.4 | 793.8 | 0.20 | 5.08 | 9 |
|  | 21033 | S | 33.6 | 823.2 | 0.80 | 20.32 | 9 |
|  | 21034 | S | 34.8 | 842.6 | 1.40 | 35.56 | 9 |
|  | 21036 | S | 36.0 | 882.0 | 2.00 | 50.80 | 9 |
|  | 21037 | S | 37.2 | 911.4 | 2.60 | 66.04 | 9 |
|  | 21038 | S | 38.4 | 940.8 | 3.20 | 81.28 | 9 |
|  | 21039 | S | 39.6 | 970.2 | 3.80 | 96.52 | 9 |
|  | 21040 | S | 40.8 | 999.6 | 0.40 | 10.16 | 11 |
|  | 21042 | S | 42.0 | 1029.0 | 1.00 | 25.40 | 11 |
|  | 21043 | S | 43.2 | 1058.4 | 1.60 | 40.64 | 11 |
|  | 21044 | S | 44.4 | 1127.8 | 2.20 | 55.88 | 11 |
|  | 21045 | S | 45.6 | 1158.2 | 2.80 | 71.12 | 11 |
|  | 21046 | S | 46.8 | 1188.7 | 3.40 | 86.36 | 11 |
|  | 21048 | S | 48.0 | 1219.2 | 4.00 | 101.6 | 11 |


| 210xxM1 |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| P/N | 210xx M1 | L (in) | L (mm) | N |
|  | 21002 M1 | 2.4 | 60.96 | 1 |
|  | 21004 M1 | 4.8 | 121.62 | 2 |
|  | 21007 M1 | 7.2 | 182.88 | 3 |
|  | 21009 M1 | 9.6 | 243.84 | 4 |
|  | 21012 M1 | 12.0 | 304.80 | 5 |
|  | 21014 M1 | 14.4 | 365.76 | 6 |
|  | 21016 M1 | 16.8 | 426.72 | 7 |
|  | 21019 M1 | 19.2 | 487.68 | 8 |
|  | 21021 M1 | 21.6 | 548.64 | 9 |
|  | 21024 M1 | 24.0 | 609.60 | 10 |
|  | 21026 M1 | 26.4 | 670.56 | 11 |
|  | 21028 M1 | 28.8 | 731.52 | 12 |
|  | 21031 M1 | 31.2 | 792.48 | 13 |
|  | 21033 M1 | 33.6 | 853.44 | 14 |
|  | 21036 M1 | 36.0 | 914.40 | 15 |
|  | 21038 M1 | 38.4 | 975.36 | 16 |
|  | 21040 M1 | 40.8 | 1036.32 | 17 |
|  | 21043 M1 | 43.2 | 1097.28 | 18 |
|  | 21045M1 | 45.6 | 1158.24 | 19 |
|  | 21048 M1 | 48.0 | 1219.20 | 20 |
| M5-0.80 x 0.300 <br> Clearance for \#8-32 or M4 Socket Head Screw |  |  |  |  |
|  |  |  |  |  |
| P/N 21002 M |  |  |  |  |


| SINGLE PIECE 210xxM |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| P/N | 210xx M | L (in) | L (mm) | N |
|  | 21002 M | 2.4 | 60.96 | 1 |
|  | 21004 M | 4.8 | 121.62 | 2 |
|  | 21007 M | 7.2 | 182.88 | 3 |
|  | 21009 M | 9.6 | 243.84 | 4 |
|  | 21012 M | 12.0 | 304.80 | 5 |
|  | 21014 M | 14.4 | 365.76 | 6 |
|  | 21016 M | 16.8 | 426.72 | 7 |
|  | 21019 M | 19.2 | 487.68 | 8 |
|  | 21021 M | 21.6 | 548.64 | 9 |
|  | 21024 M | 24.0 | 609.60 | 10 |
|  | 21026 M | 26.4 | 670.56 | 11 |
|  | 21028 M | 28.8 | 731.52 | 12 |
|  | 21031 M | 31.2 | 792.48 | 13 |
|  | 21033 M | 33.6 | 853.44 | 14 |
|  | 21036 M | 36.0 | 914.40 | 15 |
|  | 21038 M | 38.4 | 975.36 | 16 |
|  | 21040 M | 40.8 | 1036.32 | 17 |
|  | 21043 M | 43.2 | 1097.28 | 18 |
|  | 21045 M | 45.6 | 1158.24 | 19 |
|  | 21048 M | 48.0 | 1219.20 | 20 |



## WD7*



## NOTES

1. Peak force and current based on $5 \%$ duty cycle and one second duration.
2. Continuous force and current based on coil winding temperature maintained at $100^{\circ} \mathrm{C}$.
3. Force constant is peak of resistive force produced by 1.0 amp thru one motor lead and 0.5 amps thru other two leads. Also, Back EMF (V/in/sec) * $7.665=$ Force constant (lb/amp).
4. Motor resistance measured between any two motor leads with motor connected in Delta winding at $25^{\circ} \mathrm{C}$. For temperature at $100^{\circ} \mathrm{C}$, multiply resistance by $1.295\left(75^{\circ} \mathrm{C}\right.$ rise * $\left.0.393 \% /{ }^{\circ} \mathrm{C}\right)$.
5. Back EMF measured between any two motor leads while moving at constant velocity. Value is amplitude or 0-Peak of sine wave produced.
6. Motor inductance measured using 1 Kz with the motor in the magnetic field.
7. Electrical Time Constant is time it takes for motor value to reach $63 \%$ of its final current after a step change in voltage.

## WD2


*Preferred Configuration with Parker Drives
8. Thermal Time Constant is time it takes for motor temperature to reach $63 \%$ of its final value after a step change in power.
9. Thermal Resistance is the number of degrees (Celsius) of temperature rise in the winding per watt of power dissipated. Determined experimentally.
10. Motor Constant is a measure of efficiency. Calculated by dividing the force constant by the square root of the motor resistance at maximum operating temperature.
11. Electrical Cycle Length is distance coil must travel to complete $360^{\circ}$ electrical cycle.
12. Use TIPS sizing software for the most accurate estimate of coil temperature for a particular motion profile.
13. Motors available with nickel plating or black epoxy coating on magnets. Track part number modified with -N or -B at end. Must be specified at time of order.

## TFORCE

- Ironless motor, patented, RE34674
- Cross-section: 3.40 "H ( 86.4 mm ) x 1.35 "W ( 34.3 mm )
- Peak forces in two sizes to 263lbs (1170N), continuous forces to 58lbs (262N)
- Precision ground 3-piece track ( 310 model)
- Two lengths of modular magnet tracks allow unlimited length of travel
- Single-piece magnet tracks to 66" length
- Prealigned embedded digital HEDs, also available in separate cable from motor leads
- Internal air or liquid cooling available
- Internal thermal cutout switch protects coil


## PERFORMANCE

| MOTOR MODEL |  | 310-1 |  |  | 310-2 |  |  | 310-3 |  |  | 310-4 |  |  | 310-5 |  |  | 310-6 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Peak Force | N | 218.9 |  |  | 409.3 |  |  | 600.0 |  |  | 790.0 |  |  | 980.0 |  |  | 1170.0 |  |  |
|  | lb | 49.2 |  |  | 92.0 |  |  | 135.1 |  |  | 177.2 |  |  | 220.3 |  |  | 263.2 |  |  |
| Continuous Force | N | 49.0 |  |  | 91.6 |  |  | 133.9 |  |  | 176.2 |  |  | 219.3 |  |  | 262.0 |  |  |
|  | lb | 11.0 |  |  | 20.6 |  |  | 30.1 |  |  | 39.6 |  |  | 49.3 |  |  | 58.9 |  |  |
| Peak Power | W | 1077 |  |  | 1885 |  |  | 2693 |  |  | 3500 |  |  | 4308 |  |  | 5116 |  |  |
| Continuous Power | W | 54 |  |  | 94 |  |  | 135 |  |  | 179 |  |  | 215 |  |  | 256 |  |  |
| ELECTRICAL |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| MOTOR MODEL |  | 310-1 |  |  | 310-2 |  |  | 310-3 |  |  | 310-4 |  |  | 310-5 |  |  | 310-6 |  |  |
| WIRING TYPE | UNITS | S | P | T | S | P | T | S | P | T | S | P | T | S | P | T | S | P | T |
| Peak Current | $A^{\text {pk sine }}$ | 16.1 | 32.2 | 48.3 | 15.0 | 30.0 | 45.0 | 14.7 | 29.4 | 44.1 | 14.5 | 29.0 | 43.5 | 14.4 | 28.8 | 43.2 | 14.3 | 28.6 | 42.9 |
|  | (RMS) | 11.4 | 22.8 | 34.2 | 10.6 | 21.2 | 31.8 | 10.4 | 20.8 | 31.2 | 10.3 | 20.5 | 30.8 | 10.2 | 20.4 | 30.5 | 10.1 | 20.2 | 30.3 |
| Continuous Current | $A^{\text {pk sine }}$ | 3.6 | 7.2 | 10.8 | 3.4 | 6.8 | 10.2 | 3.3 | 6.6 | 9.9 | 3.2 | 6.4 | 9.6 | 3.2 | 6.4 | 9.6 | 3.2 | 6.4 | 9.6 |
|  | (RMS) | 2.5 | 5.1 | 7.6 | 2.4 | 4.8 | 7.2 | 2.5 | 4.7 | 7.0 | 2.3 | 4.5 | 6.8 | 2.3 | 4.5 | 6.8 | 2.3 | 4.5 | 6.8 |
| Force Constant | N/A peak | 13.7 | 6.8 | 4.6 | 27.3 | 13.6 | 9.1 | 40.9 | 20.5 | 13.6 | 54.7 | 27.4 | 18.2 | 68.1 | 34.0 | 22.7 | 81.8 | 40.9 | 27.3 |
|  | lb/A peak | 3.1 | 1.5 | 1.0 | 6.1 | 3.1 | 2.0 | 9.2 | 4.6 | 3.1 | 12.3 | 6.2 | 4.1 | 15.3 | 7.7 | 5.1 | 18.4 | 9.2 | 6.1 |
| Back EMF | V/m/s | 15.7 | 7.8 | 5.2 | 31.5 | 15.7 | 10.5 | 47.2 | 23.6 | 15.7 | 63.0 | 31.5 | 21.0 | 78.7 | 39.4 | 26.2 | 94.5 | 47.2 | 31.5 |
|  | V/in/s | 0.40 | 0.20 | 0.13 | 0.80 | 0.40 | 0.27 | 1.20 | 0.60 | 0.40 | 1.60 | 0.80 | 0.53 | 2.00 | 1.00 | 0.67 | 2.40 | 1.20 | 0.80 |
| Resistance $25^{\circ} \mathrm{C}$, phase to phase | ohms | 4.3 | 1.1 | 0.5 | 8.6 | 2.2 | 1.0 | 12.9 | 3.2 | 1.4 | 17.2 | 4.3 | 1.9 | 21.5 | 5.4 | 2.4 | 25.8 | 6.5 | 2.9 |
| Inductance, phase to phase | mH | 3.0 | 0.8 | 0.3 | 6.0 | 1.5 | 0.7 | 9.0 | 2.3 | 1.0 | 12.0 | 3.0 | 1.3 | 15.0 | 3.8 | 1.7 | 18.0 | 4.5 | 2.0 |
| Electrical Time Constant | ms | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 | 0.7 |
| Motor Constant | N/W | 6.67 | 6.67 | 6.67 | 9.43 | 9.43 | 9.43 | 11.57 | 11.57 | 11.57 | 13.34 | 13.34 | 13.34 | 14.95 | 14.95 | 14.95 | 16.37 | 16.37 | 16.37 |
|  | $\mathrm{lb} / \mathrm{W}$ | 1.50 | 1.50 | 1.50 | 2.12 | 2.12 | 2.12 | 2.60 | 2.60 | 2.60 | 3.00 | 3.00 | 3.00 | 3.36 | 3.36 | 3.36 | 3.68 | 3.68 | 3.68 |
| Max Terminal Voltage | VDC | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 |

NOTE: S-Series P-Parallel T-Triple
THERMAL

| MOTOR MODEL |  | $\mathbf{3 1 0 - 1}$ | $\mathbf{3 1 0 - 2}$ | $\mathbf{3 1 0 - 3}$ | $\mathbf{3 1 0 - 4}$ | $\mathbf{3 1 0 - 5}$ | $\mathbf{3 1 0 - 6}$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Thermal Resistance <br> Wind-Amb | $\mathrm{deg} / \mathrm{W}$ | 1.39 | 0.79 | 0.56 | 0.35 |  |  |
| Thermal Time <br> Constant | min | 7.5 | 7.5 | 7.5 | 7.5 | 7.5 |  |
| Maximum Winding <br> Temperature | ${ }^{\circ} \mathrm{C}$ | 100 | 100 | 100 | 100 | 100 | 100 |

MECHANICAL

| MOTOR MODEL |  | 310-1 | 310-2 | 310-3 | 310-4 | 310-5 | 310-6 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Coil Weight | kg | 0.31 | 0.55 | 0.80 | 1.03 | 1.27 | 1.53 |
|  | lb | 0.69 | 1.22 | 1.75 | 2.27 | 2.80 | 3.36 |
| Coil Length | mm | 81.3 | 142.2 | 203.2 | 264.2 | 325.1 | 386.1 |
|  | in | 3.2 | 5.6 | 8.0 | 10.4 | 12.8 | 15.2 |
| Attractive Force | N | 0 | 0 | 0 | 0 | 0 | 0 |
|  | lbf | 0 | 0 | 0 | 0 | 0 | 0 |
| Electrical Cycle | mm | 60.96 | 60.96 | 60.96 | 60.96 | 60.96 | 60.96 |
| Length | in | 2.4 | 2.4 | 2.4 | 2.4 | 2.4 | 2.4 |



Incremental Length: 2.4in/60.96mm

Minimum Length: 2.4in/60.96mm

Maximum Length: (For Single Piece) $64.8 \mathrm{in} / 1645.9 \mathrm{~mm}$
Weight/Foot:
8.501bs/ft

Incremental Length:
$2.4 \mathrm{in} / 60.96 \mathrm{~mm}$
Minimum Length:
$2.4 \mathrm{in} / 60.96 \mathrm{~mm}$
Maximum Length: 64.8in/ 1645.9 mm

Weight/Foot:
8.50lbs/ft

Incremental Length:
$1.2 \mathrm{in} / 30.48 \mathrm{~mm}$
Minimum Length:
$8.4 \mathrm{in} / 213.4 \mathrm{~mm}$
Maximum Length: $66 \mathrm{in} / 1676.4 \mathrm{~mm}$

Weight/Foot:
8.50 lbs/ft
(A) ENGLISH TOP MOUNTING


| COIL SIZE (inches) | L | N | A | B | C |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $310-1 \mathrm{~A}$ | 3.20 | 5 | 0.50 | 1.60 | 2.70 |
| $310-2 A$ | 5.60 | 5 | 0.50 | 2.80 | 5.10 |
| $310-3 A$ | 8.00 | 5 | 0.50 | 4.00 | 7.50 |
| $310-4 \mathrm{~A}$ | 10.40 | 5 | 0.50 | 5.20 | 9.90 |
| $310-5 \mathrm{~A}$ | 12.80 | 5 | 0.50 | 6.40 | 12.30 |
| $310-6 \mathrm{~A}$ | 15.20 | 5 | 1.70 | 7.60 | 13.50 |

(M) METRIC TOP MOUNTING


| COIL SIZE (mm) | L | N | A | B | C |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $310-1 M$ | 81.3 | 5 | 12.7 | 40.6 | 68.6 |
| $310-2 M$ | 141.2 | 5 | 12.7 | 71.1 | 129.5 |
| $310-3 M$ | 203.2 | 5 | 12.7 | 101.6 | 190.5 |
| $310-4 M$ | 264.2 | 5 | 12.7 | 132.1 | 251.5 |
| $310-5 M$ | 325.1 | 5 | 12.7 | 162.6 | 312.4 |
| $310-6 M$ | 386.1 | 5 | 43.2 | 193.0 | 342.9 |

## (B) ENGLISH SIDE MOUNTING



| COIL SIZE (inches) | L | N | A | B | C |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $310-1 \mathrm{~B}$ | 3.20 | 3 | 0.50 | 1.60 | 2.70 |
| $310-2 \mathrm{~B}$ | 5.60 | 3 | 0.50 | 2.80 | 5.10 |
| $310-3 \mathrm{~B}$ | 8.00 | 3 | 0.50 | 4.00 | 7.50 |
| $310-4 \mathrm{~B}$ | 10.40 | 3 | 0.50 | 5.20 | 9.90 |
| $310-5 B$ | 12.80 | 3 | 0.50 | 6.40 | 12.30 |
| $310-6 \mathrm{~B}$ | 15.20 | 3 | 1.70 | 7.60 | 13.50 |

( N ) METRIC SIDE MOUNTING


| COIL SIZE (mm) | L | N | A | B | C |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $310-1 N$ | 81.3 | 3 | 12.7 | 40.6 | 68.6 |
| $310-2 N$ | 141.2 | 3 | 12.7 | 71.1 | 129.5 |
| $310-3 N$ | 203.2 | 3 | 12.7 | 101.6 | 190.5 |
| $310-4 N$ | 264.2 | 3 | 12.7 | 132.1 | 251.5 |
| $310-5 N$ | 325.1 | 3 | 12.7 | 162.6 | 312.4 |
| $310-6 N$ | 386.1 | 3 | 43.2 | 193.0 | 342.9 |


| MODULAR TRACK |  |  |  |
| :---: | :---: | :---: | :---: |
| LENGTH | LENGTH | QUANTITY |  |
| In Inches | In mm | QUANTITY <br> 31007M <br> 31507M | 31009M <br> 31509M |
| 7.2 | 182.9 | 1 | 0 |
| 9.6 | 243.8 | 0 | 1 |
| 12.0 | 304.8 | 1 | 0 |
| 14.4 | 365.8 | 2 | 0 |
| 16.8 | 426.7 | 1 | 1 |
| 19.2 | 487.7 | 0 | 2 |
| 21.6 | 548.6 | 3 | 0 |
| 24.0 | 609.6 | 2 | 1 |
| 26.4 | 670.6 | 1 | 2 |
| 28.8 | 731.5 | 0 | 3 |
| 31.2 | 792.5 | 3 | 1 |
| 33.6 | 853.4 | 2 | 2 |
| 36.0 | 914.4 | 1 | 3 |
| 38.4 | 975.4 | 0 | 4 |
| 40.8 | 1036.3 | 3 | 2 |
| 43.2 | 1097.3 | 2 | 3 |
| 45.6 | 1158.3 | 1 | 4 |
| 48.0 | 1219.2 | 0 | 5 |
| 50.4 | 1280.2 | 3 | 3 |
| 52.8 | 1341.1 | 2 | 4 |
| 55.2 | 1402.1 | 1 | 5 |
| 57.6 | 1463.0 | 0 | 6 |
| 60.0 | 1524.0 | 3 | 4 |
| 62.4 | 1585.0 | 2 | 5 |
| 64.8 | 1645.9 | 1 | 6 |
| 67.2 | 1706.9 | 0 | 7 |
| 69.6 | 1767.8 | 3 | 5 |
| 72.0 | 1828.8 | 2 | 6 |
|  |  |  |  |

*Please note that 72.0 inches is NOT
the maximum length for modular tracks.

| 310xxS |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| P/N | 310xx | S | L (in) | L (mm) | A | A (mm) | N | P/N | 310xx | S | L (in) | L (mm) | A | A (mm) | N |
|  | 31008 | S | 8.4 | 205.8 | 0.20 | 5.08 | 3 |  | 31038 | S | 38.4 | 940.8 | 3.20 | 81.28 | 9 |
|  | 31009 | S | 9.6 | 235.2 | 0.80 | 20.32 | 3 |  | 31039 | S | 39.6 | 970.2 | 3.80 | 96.52 | 9 |
|  | 31010 | S | 10.8 | 264.6 | 1.40 | 1.40 | 3 |  | 31040 | S | 40.8 | 999.6 | 0.40 | 10.16 | 11 |
|  | 31012 | S | 12.0 | 294.0 | 2.00 | 50.80 | 3 |  | 31042 | S | 42.0 | 1029.0 | 1.00 | 25.40 | 11 |
|  | 31013 | S | 13.2 | 323.4 | 2.60 | 66.04 | 3 |  | 31043 | S | 43.2 | 1058.4 | 1.60 | 40.64 | 11 |
|  | 31014 | S | 14.4 | 352.8 | 3.20 | 81.28 | 3 |  | 31044 | S | 44.4 | 1087.8 | 2.20 | 55.88 | 11 |
|  | 31015 | S | 15.6 | 382.2 | 3.80 | 96.52 | 3 |  | 31045 | S | 45.6 | 1117.2 | 2.80 | 71.12 | 11 |
|  | 31016 | S | 16.8 | 411.6 | 0.40 | 10.16 | 5 |  | 31046 | S | 46.8 | 1146.6 | 3.40 | 86.36 | 11 |
|  | 31018 | S | 18.0 | 441.0 | 1.00 | 25.40 | 5 |  | 31048 | S | 48.0 | 1176.0 | 4.00 | 101.60 | 11 |
|  | 31019 | S | 19.2 | 470.4 | 1.60 | 40.64 | 5 |  | 31049 | S | 49.2 | 1205.4 | 0.60 | 15.24 | 13 |
|  | 31020 | S | 20.4 | 499.8 | 2.20 | 55.88 | 5 |  | 31050 | S | 50.4 | 1234.8 | 1.20 | 30.48 | 13 |
|  | 31021 | S | 21.6 | 529.2 | 2.80 | 71.12 | 5 |  | 31051 | S | 51.6 | 1264.2 | 1.80 | 45.72 | 13 |
|  | 31022 | S | 22.8 | 558.6 | 3.40 | 86.36 | 5 |  | 31052 | S | 52.8 | 1293.6 | 2.40 | 60.96 | 13 |
|  | 31024 | S | 24.0 | 588.0 | 4.00 | 101.60 | 5 |  | 31054 | S | 54.0 | 1323.0 | 3.00 | 76.20 | 13 |
|  | 31025 | S | 25.2 | 617.4 | 0.60 | 15.24 | 7 |  | 31055 | S | 55.2 | 1352.4 | 3.60 | 91.44 | 13 |
|  | 31026 | S | 26.4 | 646.8 | 1.20 | 30.48 | 7 |  | 31056 | S | 56.4 | 1381.8 | 0.20 | 5.08 | 15 |
|  | 31027 | S | 27.6 | 676.2 | 1.80 | 45.72 | 7 |  | 31057 | S | 57.6 | 1411.2 | 0.80 | 20.32 | 15 |
|  | 31028 | S | 28.8 | 705.6 | 2.40 | 60.96 | 7 |  | 31058 | S | 58.8 | 1440.6 | 1.40 | 35.56 | 15 |
|  | 31030 | S | 30.0 | 735.0 | 3.00 | 76.20 | 7 |  | 31060 | S | 60.0 | 1470.0 | 2.00 | 50.80 | 15 |
|  | 31031 | S | 31.2 | 764.4 | 3.60 | 91.44 | 7 |  | 31061 | S | 61.2 | 1499.4 | 2.60 | 66.04 | 15 |
|  | 31032 | S | 32.4 | 793.8 | 0.20 | 5.08 | 9 |  | 31062 | S | 62.4 | 1528.8 | 3.20 | 81.28 | 15 |
|  | 31033 | S | 33.6 | 823.2 | 0.80 | 20.32 | 9 |  | 31063 | S | 63.6 | 1558.2 | 3.80 | 96.52 | 15 |
|  | 31034 | S | 34.8 | 852.6 | 1.40 | 35.56 | 9 |  | 31064 | S | 64.8 | 1587.6 | 0.40 | 10.16 | 17 |
|  | 31036 | S | 36.0 | 882.0 | 2.00 | 50.80 | 9 |  | 31066 | S | 66.0 | 1617.0 | 1.00 | 25.40 | 17 |
|  | 31037 | S | 37.2 | 911.4 | 2.60 | 66.04 | 9 |  |  |  |  |  |  |  |  |


| SINGLE PIECE 310xXM |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| P/N | 310xx M | L (in) | L (mm) | N |
|  | 31002 M | 2.4 | 60.96 | 1 |
|  | 31004 M | 4.8 | 121.92 | 2 |
|  | 31007 M | 7.2 | 182.88 | 3 |
|  | 31009 M | 9.6 | 243.84 | 4 |
|  | 31012 M | 12.0 | 304.80 | 5 |
|  | 31014 M | 14.4 | 365.76 | 6 |
|  | 31016 M | 16.8 | 426.72 | 7 |
|  | 31019 M | 19.2 | 487.68 | 8 |
|  | 31021 M | 21.6 | 548.64 | 9 |
|  | 31024 M | 24.0 | 609.60 | 10 |
|  | 31026 M | 26.4 | 670.56 | 11 |
|  | 31028 M | 28.8 | 731.52 | 12 |
|  | 31031 M | 31.2 | 792.48 | 13 |
|  | 31033 M | 33.6 | 853.44 | 14 |
|  | 31036 M | 36.0 | 914.40 | 15 |
|  | 31038 M | 38.4 | 975.36 | 16 |
|  | 31040 M | 40.8 | 1036.32 | 17 |
|  | 31043 M | 43.2 | 1097.28 | 18 |
|  | 31045 M | 45.6 | 1158.24 | 19 |
|  | 31048 M | 48.0 | 1219.20 | 20 |
|  | 31050 M | 50.4 | 1280.16 | 21 |
|  | 31052 M | 52.8 | 1341.12 | 22 |
|  | 31055 M | 55.2 | 1402.08 | 23 |
|  | 31057 M | 57.6 | 1463.04 | 24 |
|  | 31060 M | 60.0 | 1524.00 | 25 |
|  | 31062 M | 62.4 | 1584.96 | 26 |
|  | 31064 M | 64.8 | 1645.92 | 27 |



## NOTES

1. Peak force and current based on $5 \%$ duty cycle and one second duration.
2. Continuous force and current based on coil winding temperature maintained at $100^{\circ} \mathrm{C}$.
3. Force constant is peak of resistive force produced by 1.0 amp thru one motor lead and 0.5 amps thru other two leads. Also, Back EMF (V/in/sec) * 7.665 = Force constant ( (b/amp).
4. Motor resistance measured between any two motor leads with motor connected in Delta winding at $25^{\circ} \mathrm{C}$. For temperature at $100^{\circ} \mathrm{C}$, multiply resistance by $1.295\left(75^{\circ} \mathrm{C}\right.$ rise * $\left.0.393 \% /{ }^{\circ} \mathrm{C}\right)$
5. Back EMF measured between any two motor leads while moving at constant velocity. Value is amplitude or 0-Peak of sine wave produced.
6. Motor inductance measured using 1 Kz with the motor in the magnetic field.
7. Electrical Time Constant is time it takes for motor value to reach $63 \%$ of its final current after a step change in voltage.


## WD4


*Preferred Configuration with Parker Drives
8. Thermal Time Constant is time it takes for motor temperature to reach $63 \%$ of its final value after a step change in power.
9. Thermal Resistance is the number of degrees (Celsius) of temperature rise in the winding per watt of power dissipated. Determined experimentally.
10. Motor Constant is a measure of efficiency. Calculated by dividing the force constant by the square root of the motor resistance at maximum operating temperature.
11. Electrical Cycle Length is distance coil must travel to complete $360^{\circ}$ electrical cycle.
12. Use TIPS sizing software for the most accurate estimate of coil temperature for a particular motion profile. 13. Motors available with nickel plating or black epoxy coating on magnets. Track part number modified with -N or -B at end. Must be specified at time of order.

I-Force Ironless Linear Motors


## TFORCE

- Ironless motor, patented, RE34674
- Cross-section: 4.50 "H ( 114.3 mm ) x 2.00"W ( 50.8 mm )
- Peak forces in two sizes to 883lbs (3928N), continuous forces to 197 lbs (878N)
- Precision ground 3-piece track (410 model)
- Two lengths of modular magnet tracks allow unlimited length of travel
- Single-piece magnet tracks to 72.24 " length
- Prealigned embedded digital HEDs, also available in separate cable from motor leads
- Internal air cooling manifold or liquid cooling manifold
- Internal thermal cutout switch protects coil

PERFORMANCE

| MOTOR MODEL |  | 410-2 | 410-3 | 410-4 | 410-6 | 410-8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Peak Force | N | 1041.4 | 1523.6 | 2006.3 | 2967.2 | 3928.1 |
|  | lb | 234.1 | 342.5 | 451.0 | 667.0 | 883.0 |
| Continuous Force | N | 233.1 | 340.8 | 448.9 | 663.7 | 878.6 |
|  | lb | 52.4 | 76.6 | 100.9 | 149.2 | 197.5 |
| Peak Power | W | 2835 | 4050 | 5265 | 7695 | 10125 |
| Continuous Power | W | 142 | 203 | 263 | 385 | 506 |

## ELECTRICAL

| MOTOR MODEL |  | 410-2 |  |  | 410-3 |  |  | 410-4 |  |  | 410-6 |  |  | 410-8 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| WIRING TYPE | UNITS | S | P | T | S | P | T | S | P | T | S | P | T | S | P | T |
| Peak Current | $A^{\text {pk sine }}$ | 19.1 | 38.2 | 57.3 | 18.6 | 37.2 | 55.8 | 18.4 | 36.8 | 55.2 | 18.1 | 36.2 | 54.3 | 18.0 | 36.0 | 54.0 |
|  | (RMS) | 13.5 | 27.0 | 40.5 | 13.2 | 23.6 | 39.5 | 13.0 | 26.0 | 39.0 | 12.8 | 25.6 | 38.4 | 12.7 | 25.5 | 38.2 |
| Continuous Current | $A^{\text {pk sine }}$ | 4.3 | 8.6 | 12.9 | 4.2 | 8.4 | 12.6 | 4.1 | 8.2 | 12.3 | 4.1 | 8.2 | 12.3 | 4.0 | 8.0 | 12.0 |
|  | (RMS) | 3.0 | 6.1 | 9.1 | 3.0 | 5.9 | 8.9 | 2.9 | 5.8 | 8.7 | 2.9 | 5.8 | 5.7 | 2.8 | 5.7 | 8.5 |
| Force Constant | N/A peak | 54.5 | 27.3 | 18.2 | 81.8 | 40.9 | 27.3 | 109.0 | 54.5 | 36.3 | 163.7 | 81.8 | 54.6 | 218.4 | 109.2 | 72.8 |
|  | lb/A peak | 12.3 | 6.1 | 4.1 | 18.4 | 9.2 | 6.1 | 24.5 | 12.3 | 8.2 | 36.8 | 18.4 | 12.3 | 49.1 | 24.6 | 16.4 |
| Back EMF | V/m/s | 63.0 | 31.5 | 21.0 | 94.5 | 47.2 | 31.5 | 126.0 | 63.0 | 42.0 | 189.0 | 94.5 | 63.0 | 252.0 | 126.0 | 84.0 |
| V/in/s |  | 1.60 | 0.80 | 0.53 | 2.40 | 1.20 | 0.80 | 3.20 | 1.60 | 1.07 | 4.80 | 2.40 | 1.60 | 6.40 | 3.20 | 2.13 |
| Resistance $25^{\circ} \mathrm{C}$, phase to phase | ohms | 8.0 | 2.0 | 0.9 | 12.0 | 3.0 | 1.3 | 16.0 | 4.0 | 1.8 | 24.0 | 6.0 | 2.7 | 32.0 | 8.0 | 3.6 |
| Inductance, phase to phase | mH | 10.0 | 2.5 | 1.1 | 15.0 | 3.8 | 1.7 | 20.0 | 5.0 | 2.2 | 30.0 | 7.5 | 3.3 | 40.0 | 10.0 | 4.4 |
| Electrical Time Constant | ms | 1.3 | 1.3 | 1.3 | 1.3 | 1.3 | 1.3 | 1.3 | 1.3 | 1.3 | 1.3 | 1.3 | 1.3 | 1.3 | 1.3 | 1.3 |
| Motor Constant | N/W | 19.57 | 19.57 | 19.57 | 23.98 | 23.98 | 23.98 | 27.67 | 27.67 | 27.67 | 33.90 | 33.90 | 33.90 | 39.14 | 39.14 | 39.14 |
|  | lb/W | 4.40 | 4.40 | 4.40 | 5.39 | 5.39 | 5.39 | 6.22 | 6.22 | 6.22 | 7.62 | 7.62 | 7.62 | 8.80 | 8.80 | 8.80 |
| Max Terminal Voltage | VDC | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 | 330 |

NOTE: S-Series P-Parallel T-Triple
THERMAL

| MOTOR MODEL |  | $\mathbf{4 1 0 - 2}$ | $\mathbf{4 1 0 - 3}$ | $\mathbf{4 1 0 - 4}$ | $\mathbf{4 1 0 - 6}$ | $\mathbf{4 1 0 - 8}$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Thermal Resistance <br> Wind-Amb | degC $/$ W | 0.53 | 0.37 | 0.19 |  |  |
| Thermal Time <br> Constant | min | 15.1 | 15.1 | 15.1 | 15.1 |  |
| Maximum Winding <br> Temperature | ${ }^{\circ} \mathrm{C}$ | 100 | 100 | 100 | 100 |  |

MECHANICAL

| MOTOR MODEL |  | 410-2 | 410-3 | 410-4 | 410-6 | 410-8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Coil Weight | kg | 1.59 | 2.27 | 2.95 | 4.32 | 5.68 |
|  | lb | 3.5 | 5.0 | 6.5 | 9.5 | 12.5 |
| Coil Length | mm | 199.1 | 284.5 | 369.8 | 540.5 | 711.2 |
|  | in | 7.84 | 11.20 | 14.56 | 21.28 | 28.00 |
| Attractive Force | N | 0 | 0 | 0 | 0 | 0 |
|  | lbf | 0 | 0 | 0 | 0 | 0 |
| Electrical Cycle | mm | 85.34 | 85.34 | 85.34 | 85.34 | 85.34 |
| Length | in | 3.36 | 3.36 | 3.36 | 3.36 | 3.36 |


(A) ENGLISH TOP MOUNTING


| COIL SIZE (in) | L | N | $\mathbf{A}$ | $\mathbf{B}$ | $\mathbf{C}$ | $\mathbf{D}$ | $\mathbf{E}$ | F | G |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $410-2 A$ | 7.84 | 5 | 0.50 | 3.92 | 7.34 | --- | --- | --- | --- |
| $410-3 \mathrm{~A}$ | 11.20 | 8 | 0.50 | 1.60 | 5.60 | 9.60 | 10.70 | --- | --- |
| $410-4 \mathrm{~A}$ | 14.56 | 9 | 0.50 | 3.28 | 7.28 | 11.28 | 14.06 | --- | --- |
| $410-6 \mathrm{~A}$ | 21.28 | 13 | 0.50 | 2.64 | 6.64 | 10.64 | 14.64 | 18.64 | 20.78 |
| $410-8 \mathrm{~A}$ | 28.00 | 13 | 2.00 | 6.00 | 10.00 | 14.00 | 18.00 | 22.00 | 26.00 |

(M) METRIC TOP MOUNTING


| COIL SIZE (mm) L | N | A | B | C | D | E | F | G |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $410-2 M$ | 199.1 | 5 | 12.7 | 99.6 | 186.4 | --- | --- | --- | --- |
| $410-3 M$ | 284.5 | 8 | 12.7 | 40.6 | 142.2 | 243.8 | 271.8 | --- | --- |
| $410-4 M$ | 369.8 | 9 | 12.7 | 83.3 | 184.9 | 286.5 | 357.1 | --- | --- |
| $410-6 \mathrm{M}$ | 540.5 | 13 | 12.7 | 67.1 | 168.7 | 270.3 | 371.9 | 473.4 | 527.8 |
| $410-8 \mathrm{M}$ | 711.2 | 13 | 50.8 | 152.4 | 254.0 | 355.6 | 457.2 | 558.8 | 660.4 |

B) ENGLISH SIDE MOUNTING

| COIL SIZE (in) | L | N | A | B | C | D | E | F | G | H | I |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 410-2B | 7.84 | 3 | 2.90 | 4.90 | 6.90 | --- | --- | --- | --- | --- | --- |
| 410-3B | 11.20 | 3 | 4.10 | 7.10 | 10.10 | --- | --- | --- | --- | --- | --- |
| 410-4B | 14.56 | 4 | 2.78 | 5.78 | 8.78 | 11.78 | --- | --- | --- | --- | --- |
| 410-6B | 21.28 | 6 | 3.14 | 6.14 | 9.14 | 12.14 | 15.14 | 18.14 | --- | --- | --- |
| 410-8B | 28.00 | 9 | 3.50 | 6.50 | 9.50 | 12.50 | 15.50 | 18.50 | 21.50 | 24.50 | 27.50 |

## (N) METRIC SIDE MOUNTING



| COIL SIZE (mm) | L | N | A | B | C | D | E | F | G | H | I |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $410-2 N$ | 199.1 | 3 | 73.7 | 124.5 | 175.3 | --- | --- | --- | --- | --- | --- |
| $410-3 N$ | 284.5 | 3 | 104.1 | 180.3 | 256.5 | --- | --- | --- | --- | --- | --- |
| $410-4 N$ | 369.8 | 4 | 70.6 | 146.8 | 223.0 | 299.2 | --- | --- | --- | --- | --- |
| $410-6 N$ | 540.5 | 6 | 79.7 | 156.0 | 232.2 | 308.4 | 384.6 | 460.8 | --- | --- | --- |
| $410-8 N$ | 711.2 | 9 | 88.9 | 165.1 | 241.3 | 317.5 | 393.7 | 469.9 | 546.1 | 622.3 | 698.5 |


| LENGTH <br> Inches | MODULAR TRACK |  |  |
| :---: | :---: | :---: | :---: |
|  | LENGTH <br> In mm | QUANTITY <br> 41006M | QUANTITY <br> 41010M |
| 6.72 | 170.69 | 1 | 0 |
| 10.08 | 256.03 | 0 | 1 |
| 13.44 | 341.38 | 0 | 0 |
| 16.80 | 426.72 | 1 | 1 |
| 20.16 | 512.06 | 0 | 2 |
| 23.52 | 597.41 | 2 | 1 |
| 26.88 | 682.75 | 1 | 2 |
| 30.24 | 768.10 | 0 | 3 |
| 33.60 | 853.44 | 2 | 2 |
| 36.96 | 938.78 | 1 | 3 |
| 40.32 | 1024.13 | 0 | 4 |
| 43.68 | 1109.47 | 2 | 3 |
| 47.04 | 1194.82 | 1 | 4 |
| 50.40 | 1280.16 | 0 | 5 |
| 53.76 | 1365.50 | 2 | 4 |
| 57.12 | 1450.85 | 1 | 5 |
| 60.48 | 1536.19 | 0 | 6 |
| 63.84 | 1621.54 | 2 | 5 |
| 67.20 | 1706.88 | 1 | 6 |
| 70.56 | 1792.22 | 0 | 7 |
| 73.92 | 1877.57 | 2 | 6 |
| 77.28 | 1962.91 | 1 | 7 |
| 80.64 | 2048.26 | 0 | 8 |
| 84.00 | 2133.60 | 2 | 7 |
| 87.36 | 2218.94 | 1 | 8 |
| 90.72 | 2304.29 | 0 | 9 |
| 94.08 | 2389.63 | 2 | 8 |
| 97.44 | 2474.98 | 1 | 9 |



P/N 41003 M


| 410 xx M1 |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| P/N | 410xx M1 | L (in) | L (mm) | N |
|  | 41006 M1 | 6.72 | 170.69 | 2 |
|  | 41010 M1 | 10.08 | 256.03 | 3 |
|  | 41013 M1 | 13.44 | 341.38 | 4 |
|  | 41016 M1 | 16.80 | 426.72 | 5 |
|  | 41020 M1 | 20.16 | 512.06 | 6 |
|  | 41023 M1 | 23.52 | 597.41 | 7 |
|  | 41026 M1 | 26.88 | 682.75 | 8 |
|  | 41030 M1 | 30.24 | 768.10 | 9 |
|  | 41033 M1 | 33.60 | 853.44 | 10 |
|  | 41036 M1 | 36.96 | 938.78 | 11 |
|  | 41040 M1 | 40.32 | 1024.13 | 12 |
|  | 41043 M1 | 43.68 | 1109.47 | 13 |
|  | 41047 M1 | 47.04 | 1194.82 | 14 |
|  | 41050 M1 | 50.40 | 1280.16 | 15 |
|  | 41053 M1 | 53.76 | 1365.50 | 16 |
|  | 41057 M1 | 57.12 | 1450.85 | 17 |
|  | 41060 M1 | 60.48 | 1536.19 | 18 |
|  | 41063 M1 | 63.84 | 1621.54 | 19 |
|  | 41067 M1 | 67.20 | 1706.88 | 20 |
|  | 41070 M1 | 70.56 | 1792.22 | 21 |


| SINGLE PIECE 410xxM |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| P/N | 410xx | M | L (in) | L (mm) | N |
|  | 41003 | M | 3.36 | 85.34 | 1 |
|  | 41006 | M | 6.72 | 170.69 | 2 |
|  | 41010 | M | 10.08 | 256.03 | 3 |
|  | 41013 | M | 13.44 | 341.38 | 4 |
|  | 41016 | M | 16.80 | 426.72 | 5 |
|  | 41020 | M | 20.16 | 512.06 | 6 |
|  | 41023 | M | 23.52 | 597.41 | 7 |
|  | 41026 | M | 26.88 | 682.75 | 8 |
|  | 41030 | M | 30.24 | 768.10 | 9 |
|  | 41033 | M | 33.60 | 853.44 | 10 |
|  | 41036 | M | 36.96 | 938.78 | 11 |
|  | 41040 | M | 40.32 | 1024.13 | 12 |
|  | 41043 | M | 43.68 | 1109.47 | 13 |
|  | 41047 | M | 47.04 | 1194.82 | 14 |
|  | 41050 | M | 50.40 | 1280.16 | 15 |
|  | 41053 | M | 53.76 | 1365.50 | 16 |
|  | 41057 | M | 57.12 | 1450.85 | 17 |
|  | 41060 | M | 60.48 | 1536.19 | 18 |
|  | 41063 | M | 63.84 | 1621.54 | 19 |
|  | 41067 | M | 67.20 | 1706.88 | 20 |
|  | 41070 | M | 70.56 | 1792.22 | 21 |

## WD1



## WD3



## NOTES

1. Peak force and current based on $5 \%$ duty cycle and one second duration.
2. Continuous force and current based on coil winding temperature maintained at $100^{\circ} \mathrm{C}$.
3. Force constant is peak of resistive force produced by 1.0 amp thru one motor lead and 0.5 amps thru other two leads. Also, Back EMF (V/in/sec) * 7.665 = Force constant (Ib/amp).
4. Motor resistance measured between any two motor leads with motor connected in Delta winding at $25^{\circ} \mathrm{C}$. For temperature at $100^{\circ} \mathrm{C}$, multiply resistance by $1.295\left(75^{\circ} \mathrm{C}\right.$ rise * $\left.0.393 \% /{ }^{\circ} \mathrm{C}\right)$
5. Back EMF measured between any two motor leads while moving at constant velocity. Value is amplitude or 0-Peak of sine wave produced
6. Motor inductance measured using 1 Kz with the motor in the magnetic field.
7. Electrical Time Constant is time it takes for motor value to reach $63 \%$ of its final current after a step change in voltage.

## WD2


8. Thermal Time Constant is time it takes for motor temperature to reach $63 \%$ of its final value after a step change in power.
9. Thermal Resistance is the number of degrees (Celsius) of temperature rise in the winding per watt of power dissipated. Determined experimentally.
10. Motor Constant is a measure of efficiency. Calculated by dividing the force constant by the square root of the motor resistance at maximum operating temperature
11. Electrical Cycle Length is distance coil must travel to complete $360^{\circ}$ electrical cycle
12. Use TIPS sizing software for the most accurate estimate of coil temperature for a particular motion profile.
13. Motors available with nickel plating or black epoxy coating on magnets. Track part number modified with -N or -B at end. Must be specified at time of order.

## Motor Coil

Order Example:


## Magnet Track:

$$
\begin{array}{lll}
\text { 110xxM: } 11007 \mathrm{M}, 11009 \mathrm{M} & 7.20 ", 9.60 & \text { modular sections } \\
\text { 11507M: } 11507 \mathrm{M}, 11509 \mathrm{M} & 7.20 ", \text {, } 9.60 & \text { modular sections } \\
\text { 110xxM1: 11036M1, max } & 36.00 " \text { max } & \text { single piece, } 2.4 \text { " incr. } \\
\text { 110xxM: 11036M, max } & 36.00 " \text { max } & \text { single piece, 2.4" incr. } \\
\text { 115xxM: 11524M, max } & 24.00 " \text { max } & \text { single piece, 2.4" incr. } \\
\text { 110xxS: 11036M, max } & 36.00 " \text { max } & \text { single piece, } 1.2^{"} \text { incr. }
\end{array}
$$



## Motor Coil



## Magnet Track:

210xxM: 21007M, 21009M 21507M: 21507M, 21509M 210xxM1: 21048M1 max 210xxM: 21048M max 215xxM: 21524M max 210xxS: 21048S max
7.20", 9.60" modular sections $7.20^{\prime \prime}, 9.60$ " modular sections 48.00 " max single piece, $2.4^{\prime \prime}$ incr. 48.00 " max single piece, $2.4^{\prime \prime}$ incr. $24.00^{\prime \prime}$ max single piece, $2.4^{\prime \prime}$ incr. $48.00^{\prime \prime}$ max single piece, 1.2" incr.


## Motor Coil

Order Example:


## Magnet Track:

310xxM: 31007M, 31009M $\quad 7.20$ ", 9.60 " modular sections
31507M: 31507M, 31509M 7.20", 9.60" modular sections 310xxM1: 31064M1 max 310xxM: 31064M max 315xxM: 31524 M max $\quad 24.00^{\prime \prime}$ max single piece, $2.4^{\prime \prime}$ incr. $64.8^{\prime \prime}$ max single piece, $2.4^{\prime \prime}$ incr. 310xxS: $\quad 31066 S$ max $\quad 64.8^{\prime \prime}$ max single piece, 1.2" incr.


## Motor Coil



## Magnet Track:

```
410xxM: 41006M, 41010M 6.72", 10.08" modular sections
410xxM1: 41070M1max
410xxM: 41070M max
    70.56" max single piece, 3.36" incr.
    70.56" max single piece, 3.36" incr.
    70.56" max single piece, 1.68"
```



Additional information available on:
www.parker-eme.com/trilogy_motor

## I-FORCE Ironless Linear Positioners



Parker Trilogy's I-Force linear positioners utilize our high-performance I-Force ironless linear motors in a pre-engineered, easily integrated, ready-to-run package. The principal design goal for these positioners is to achieve high performance at an economical cost while preserving the design flexibility to accommodate customization.

Trilogy's positioners have selectable single- or dual-bearing to match the performance and cost requirements for each application. In addition, they are designed to connect together using transition plates for XY or multi-axis configurations. Options include a variety of cable management systems in addition to bellows and hard covers.

Flexibility, multi-axis compatibility, and ease of customization make the l-Force linear positioners a superior choice for high performance and value.

- Trilogy positioners use ground steel or aluminum bases for flatness and parallelism because aluminum extrusions often do not meet the accuracy requirements for straightness and flatness.
- Trilogy has single- or dual-bearing rail positioners to better match the performance and cost requirements for each application.
- Every positioner includes a magnetic encoder for industrial environments or an optical encoder with resolutions down to 0.1 um ( 0.00004 ").
- Dual-rail positioners have bellows as a standard option.
- Multiple carriage options are available on all positioner series.
- Different cable track widths available for added stiffness and rigidity
- Different cable track widths available as custom options for user payload tubes and cables


| MOTOR MODEL |  | $\mathbf{1 1 0 - 1}$ | $\mathbf{1 1 0 - 2}$ |
| :--- | :---: | :---: | :---: |
| Peak Force | N | 108.5 | 202.5 |
| Continuous Force | b | 24.4 | 45.5 |
| Peak Power | N | 24.5 | 45.4 |
| Continuous Power | W | 5.5 | 10.2 |


| ACCURACY | STANDARD | LASER ALIGNMENT OPTION |
| :--- | :---: | :---: |
| Straightness restrained on flat surface in $[\mu \mathrm{m}]$ | $\pm 0.000127 \mathrm{in} / \mathrm{in}[ \pm 127 \mu \mathrm{~m} / \mathrm{m}]$ | $\pm .0000127 \mathrm{in} / \mathrm{in}$ |
| Flatness restrained on flat surface in $[\mu \mathrm{m}]$ | $\pm 0.013[ \pm 330]$ |  |

Note: Straightness/Flatness specifications based on system mounted to surface of flatness $\pm 0.0005 \mathrm{in} / \mathrm{ft}$

| LOAD |  | - 1 | - 2 |
| :--- | :--- | :--- | :--- |
| Vertical (Fv) see note 11 | $\mathrm{lbs}[\mathrm{kg}]$ | $30[13,5]$ | $30[13,5]$ |
| Side (Fs) see note 11 | $\mathrm{lbs}[\mathrm{kg}]$ | $15[6,8]$ | $15[6,8]$ |
| Moments-Roll (Mr) see note 11 | $\mathrm{lb} \mathrm{ft}[\mathrm{N}-\mathrm{m}]$ | $15[20]$ | $15[20]$ |
| Moments-Pitch $(\mathrm{Mp})$ see note 11 | $\mathrm{lb}-\mathrm{ft}[\mathrm{N}-\mathrm{m}]$ | $52[70]$ | $52[70]$ |
| Moments-Yaw (My) see note 11 | $\mathrm{lb}-\mathrm{ft}[\mathrm{N}-\mathrm{m}]$ | $52[70]$ | $52[70]$ |

## Dimensions shown in inches.

- Moving Carriage Assembly
- Stationary Base Assembly


+LIMIT
( $\sim 0.1$ FROM HARD STOP)
(2.54)
0.125
(3.175)

TOTAL TRAVEL $=$ OAL $-0.200 "(50.8 \mathrm{~mm})-$ CARRIAGE LENGTH OAL = BASE LENGTH + 0.250" ( 6.35 mm )
BASE LENGTH = MULTIPLE OF 2.400" (60.96)

CARRIAGE SIZE

| CARRIAGE SIZE |  |  |  |  |
| :---: | :---: | :---: | :---: | ---: |
| CL | $\mathbf{- 1}$ | $\mathbf{m m}$ | $\mathbf{- 2}$ | $\mathbf{m m}$ |
| B | 0.730 | 137.16 | 7.800 | 198.12 |
| Coil | $110-59$ | 1.932 | 49.07 |  |

## I-Force Ironless

 Motor Positioner

| MOTOR MODEL |  | $\mathbf{1 1 0 - 1}$ | $\mathbf{1 1 0 - 2}$ |
| :--- | :---: | :---: | :---: |
| Peak Force | N | 108.5 | 202.5 |
| Continuous Force | lb | 24.4 | 45.5 |
| Peak Power | N | 24.5 | 45.4 |
| Continuous Power | W | 5.5 | 10.2 |


| ACCURACY | STANDARD | LASER ALIGNMENT OPTION |
| :--- | :---: | :---: |
| Straightness restrained on flat surface in $[\mu \mathrm{m}]$ | $\pm 0.000127 \mathrm{in} / \mathrm{in}[ \pm 127 \mu \mathrm{~m} / \mathrm{m}]$ | $\pm .000013 \mathrm{in} / \mathrm{in}[ \pm 13 \mu \mathrm{~m} / \mathrm{m}]$ |
| Flatness restrained on flat surface in $[\mu \mathrm{m}]$ | $\pm 0.013[ \pm 330]$ |  |
| Note: Straightness/Flatess specifications based on system mounted to surface of flatess $+0.0005 \mathrm{in} / \mathrm{t}$ |  |  |

Note: Straightness/Flatness specifications based on system mounted to surface of flatness $\pm 0.0005 \mathrm{in} / \mathrm{ft}$

| PHYSICAL |  | - 2 | - 3 |
| :---: | :---: | :---: | :---: |
| Carriage Assembly | lbs [kg] | $1.10[0,50]$ | $1.50[0,68]$ |
| Base Assembly |  |  |  |
| T1SD Aluminum (0.250" thick)) | lbs/tt [kg/m] | $2.25[3,35]$ | $\ldots$ |
| T1SA Aluminum ( $0.375^{\prime \prime}$ thick)) | $\mathrm{lbs} / \mathrm{tt}[\mathrm{kg} / \mathrm{m}]$ | 2.78. [4,13] | .......... |
| Carriage Length | in [mm] | 3.40 [86,4] | 5.80 [147,3] |
| Coil Bar Length | in [mm] | 3.20 [81,3] | 5.60 [142,2] |
| LOAD |  | - 1 | - 2 |
| Vertical (Fv) see note 11 | lbs [kg] | $25[11,3]$ | $25[11,3]$ |
| Side (Fs) see note 11 | lbs [kg] | $13[5,7]$ | $13[5,7]$ |
| Moments-Roll (Mr) see note 11 | lb-ft [ $\mathrm{N}-\mathrm{m}$ ] | 11 [15] | 11 [15] |
| Moments-Pitch (Mp) see note 11 | lb-ft [ $\mathrm{N}-\mathrm{m}$ ] | 44 [60] | 44 [60] |
| Moments-Yaw (My) see note 11 | lb-ft [N-m] | 44 [60] | 44 [60] |

## NOTES

1 Total travel (in) = BASE LENGTH - 1.6 ( 40.64 mm ) - CARRIAGE LENGTH.
2 Maximum base length is $40.8^{\prime \prime}, 1 \mathrm{~m}$
3 Aluminum base is black anodized.
4 For complete motor specifications, refer to 110 series motor data sheet.
5 Renishaw encoder, RGH24 series, available in $0.05 \mu \mathrm{~m}, 0.1 \mu \mathrm{~m}, 0.5 \mu \mathrm{~m}$, $1.0 \mu \mathrm{~m}, 5.0 \mu \mathrm{~m}$.

7 Standard cable track provided is Igus 07.20.018.
8 Specification subject to change without notice.
9 Listed specifications based on motor size and typical performance requirements. Bearing manufacturer specifications exceed listed specifications.

T1S

CARRIAGE TABLE
OAI = BASE LENGTH $+1.25 \mathrm{IN}(31.75)$
TRAVEL $=$ BASE LENGTH $-1.6-$ CARRIAGE LENGTH TRAVEL $(\mathrm{mm})=$ BASE LENGTH $-40.64-$ CARRIAGE LENGTH

| CARRIAGE TABLE |  |  |  |
| :--- | :--- | :--- | :---: |
| COIL SIZE | $\mathbf{- 1}$ | $\mathbf{- 2}$ |  |
| CARRIAGE LENGTH | $3.4[86.4]$ | $5.8[147.3]$ |  |
| A (1ST MOUNTING HOLE) | $0.224[5.7]$ | $0.440[11.2]$ |  |
| B (DOWEL PIN HOLE) | $0.224[5.7]$ | $0.440[11.2]$ |  |

## I-Force Ironless Motor Positioner

| PERFORMANCE |  | LINEAR MAGNETC ENCODER5.0um1.0 um |  | RENSHAW ENCODER OPTIONS (Note 5)0.5 um0.1 um |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Peak Velocity | in/s [m/s] | 275 [7] | 100 [2.5] | 120 [3] | 15 [0.4] |
| Resolution | in [ $\mu \mathrm{m}$ ] | 0.0002 [5] | 0.00004 [1.0] | $0.00002[0.5]$ | 0.000004 [0.1] |
| Repeatability | in [ $\mu \mathrm{m}$ ] | $\pm 0.0004[ \pm 10]$ | $\pm 0.0008$ [2.0] | $\pm 0.00006$ [1.5] | $\pm 0.00004$ [1.0] |
| Accuracy - LME |  | 30 $\mu \mathrm{m}+50 \mu \mathrm{~m} / \mathrm{m}$ | $(25 \mu \mathrm{~m}+50 \mu \mathrm{~m} / \mathrm{m}$ |  |  |
| Accuracy - Renishaw |  |  |  | $\pm(5 \mu \mathrm{~m}+$ | $\mathrm{m} / \mathrm{m}$ ) |
| Note: For travels less than 1 meter, accuracy should be calculated at 1 meter |  |  |  |  |  |
| MOTOR MODEL |  | 210-2 | 210-3 | 210-4 |  |
| Peak Force | N | 255.8 | 375.0 | 494.2 |  |
|  | lb | 57.5 | 84.3 | 111.1 |  |
| Continuous Force | N | 57.4 | 84.1 | 110.3 |  |
|  | lb | 12.9 | 18.9 | 24.8 |  |
| Peak Power | W | 1583 | 2261 | 2940 |  |
| Continuous Power | W | 79 | 113 | 147 |  |



| LOAD |  | - 2 | - 3 | - 4 |
| :---: | :---: | :---: | :---: | :---: |
| Vertical (Fv) see note 11 | lbs [kg] | 60 [27,1] | $80[36,3]$ | 100 [45,3] |
| Side (Fs) see note 11 | lbs [kg] | $40[18,1]$ | $60[27,2]$ | $60[27,2]$ |
| Moments-Roll (Mr) see note 11 | $\mathrm{lb}-\mathrm{ft}[\mathrm{N}-\mathrm{m}]$ | 40 [53] | 60 [80] | 60 [80] |
| Moments-Pitch (Mp) see note 11 | $\mathrm{lb}-\mathrm{ft}[\mathrm{N}-\mathrm{m}]$ | 100 [134] | 200 [270] | 200 [270] |
| Moments-Yaw (My) see note 11 | $\mathrm{lb}-\mathrm{ft}[\mathrm{N}-\mathrm{m}]$ | 100 [134] | 200 [270] | 200 [270] |

## NOTES

1 Total travel $=0 \mathrm{AL}-3.00^{\prime \prime}(76.2 \mathrm{~mm})$ - carriage length.
2 Maximum base length is $120^{\prime \prime}(3048 \mathrm{~mm})$.
3 Aluminum base is black anodized. Steel base is nickel plated.
4 For complete motor specifications, refer to 210 series motor data sheet.
5 Renishaw encoder, RGH24 series, available in $0.05 \mu \mathrm{~m}, 0.1 \mu \mathrm{~m}, 0.5 \mu \mathrm{~m}$, $1.0 \mu \mathrm{~m}, 5.0 \mu \mathrm{~m}$.
6 Cables extend past base by approximately $0.6^{\prime \prime}$ when carriage is at negative hard stop.

7 Cable Track extends $0.175^{\prime \prime}$ higher than carriage mounting surface. It is recommended to use optional Spacer Plate for custom mounting holes.
8 Standard cable track provided is Igus 07.30.018.
9 Base mounting holes are equidistant, $1.200^{\prime \prime}$ ( $12.0,16.8,21.6 \ldots$...) or $2.400^{\prime \prime}(9.6,14.4,19.2,24.0 \ldots .$.$) from each end depending on base length.$
10 Specification subject to change without notice.
11 Listed specifications based on motor size and typical performance requirements. Bearing manufacturer specifications exceed listed specifications.

## Dimensions shown in inches.

- Moving Carriage Assembly
- Stationary Base Assembly


TOTAL TRAVEL = OAL - 3.00" $(76.2 \mathrm{~mm})-$ CARRIAGE LENGTH
OAL = MULTIPLE OF 2.400" (60.96)

| CARRIAGE SIZE |  |  |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{- 2}$ | $\mathbf{m m}$ | $\mathbf{- 3}$ | $\mathbf{m m}$ | $\mathbf{- 4}$ | $\mathbf{m m}$ |
| CL | 4.200 | 106.68 | 6.600 | 167.64 | 9.000 | 228.6 |
| A | 3.200 | 81.28 | 5.600 | 142.24 | 8.000 | 203.80 |
| B | - | - | 2.800 | 71.12 | 4.000 | 101.60 |
| COIL | $210-2$ | $210-3$ | $210-4$ |  |  |  |



## I-Force Ironless Motor Positioner

## T2S Specifications

| PERFORMANCE |  | $\begin{aligned} & \text { LINEAR MAGNETIC ENCODER } \\ & 5.0 \mathrm{um} \\ & 1.0 \mathrm{um} \end{aligned}$ |  | RENSHAW ENCODER OPTIONS (Note 5)0.5 um0.1 mm |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Peak Velocity | $\mathrm{in} / \mathrm{s}[\mathrm{m} / \mathrm{s}]$ | 275 [7] | 100 [2.5] | 120 [3] | 15 [0.4] |
| Resolution | in [ $\mu \mathrm{m}$ ] | 0.0002 [5] | 0.00004 [1.0] | 0.00002 [0.5] | 0.000004 [0.1] |
| Repeatability | in [ $\mu \mathrm{m}$ ] | $\pm 0.0004[ \pm 10]$ | $\pm 0.0008$ [2.0] | $\pm 0.00006[1.5]$ | $\pm 0.00004$ [1.0] |
| Accuracy - LME |  | $\pm(30 \mu \mathrm{~m}+50 \mu \mathrm{~m} / \mathrm{m}) \quad \pm(25 \mu \mathrm{~m}+50 \mu \mathrm{~m} / \mathrm{m})$ |  |  |  |
| Accuracy - Renishaw |  |  |  | $\pm(5 \mu \mathrm{~m}+30 \mu \mathrm{~m} / \mathrm{m})$ |  |
| Note: For travels less than 1 | should be calc | at 1 meter |  |  |  |


| MOTOR MODEL |  | $\mathbf{2 1 0 - 2}$ | $\mathbf{2 1 0 - 3}$ | $\mathbf{2 1 0 - 4}$ |
| :--- | :---: | :---: | :---: | :---: |
| Peak Force | N | 255.8 | 375.0 | 494.2 |
|  | lb | 57.5 | 84.3 | 111.1 |
| Continuous Force | N | 57.4 | 84.1 | 110.3 |
| Peak Power | lb | 12.9 | 18.9 | 24.8 |
| Continuous Power | W | 1583 | 2261 | 2940 |


| ACCURACY | STANDARD | LASER ALIGNMENT OPTION |
| :--- | :---: | :---: |
| Straightness restrained on flat surface in $[\mu \mathrm{m}]$ | $\pm 0.000127 \mathrm{in} / \mathrm{m}[ \pm 127 \mathrm{~mm} / \mathrm{m}]$ | $\pm 0.0000127 \mathrm{in} / \mathrm{in}[ \pm 13 \mathrm{~mm} / \mathrm{m}]$ |
| Flatness restrained on flat surface in $[\mu \mathrm{m}]$ | $\pm 0.003+.000254 \mathrm{in} / \mathrm{in}[ \pm 76+254 \mu \mathrm{~m} / \mathrm{m}]$ |  |

```
Note: For travels less than 1 meter, Flatness should be calculated at 1 meter
    Straightness/Flatness specifications based on system mounted to surface of flatness }\pm0.0005\mathrm{ in/ft
```

| PHYSICAL |  | - 2 | - 3 | - 4 |
| :---: | :---: | :---: | :---: | :---: |
| Carriage Assembly | lbs [kg] | 2.10 [0,95] | 3.10 [1,38] | 3.80 [1,70] |
| Base Assembly |  |  | - | .......) |
| T2SA Aluminum (0.375" thick) | $\mathrm{lbs} / \mathrm{tt}[\mathrm{kg} / \mathrm{m}]$ | 9.10 [13,5] | - |  |
| T2SB Aluminum ( 0.500 " thick) | $\mathrm{lbs} / \mathrm{tt}[\mathrm{kg} / \mathrm{m}]$ | 9.90 [14,7] |  |  |
| T2SS Steel ( $0.500^{\prime \prime}$ thick) | $\mathrm{lbs} / \mathrm{tt}[\mathrm{kg} / \mathrm{m}]$ | 15.10 [22,5] | - | - |
| Carriage Length | in [mm] | 4.20 [106,7] | $6.60[167,6]$ | $9.00[228,6]$ |
| Coil Bar Length | in [mm] | 7.20 [182,9] | 9.60 [243,8] | 12.00 [304,8] |


| LOAD |  | - 2 | - 3 | - 4 |
| :---: | :---: | :---: | :---: | :---: |
| Vertical (Fv) see note 11 | lbs [kg] | 40 [18,1] | $50[22,7]$ | $60[27,2]$ |
| Side (Fs) see note 11 | lbs [kg] | $20[9,1]$ | $30[13,6]$ | $30[13,6]$ |
| Moments-Roll (Mr) see note 11 | lb -ft [ $\mathrm{N}-\mathrm{m}$ ] | 20 [27] | 30 [40] | 30 [40] |
| Moments-Pitch (Mp) see note 11 | lb -ft [ $\mathrm{N}-\mathrm{m}$ ] | 50 [67] | 100 [135] | 100 [135] |
| Moments-Yaw (My) see note 11 | lb -ft [ $\mathrm{N}-\mathrm{m}$ ] | 50 [67] | 100 [135] | 100 [135] |

## NOTES

1 Total travel $=0 \mathrm{AL}-3.00^{\prime \prime}(76.2 \mathrm{~mm})-$ carriage length.
2 Maximum base length is $120^{\prime \prime}(3048 \mathrm{~mm})$.
3 Aluminum base is black anodized. Steel base is nickel plated.
4 For complete motor specifications, refer to 210 series motor data sheet.
5 Renishaw encoder, RGH24 series, available in $0.05 \mu \mathrm{~m}, 0.1 \mu \mathrm{~m}, 0.5 \mu \mathrm{~m}$, $1.0 \mu \mathrm{~m}, 5.0 \mu \mathrm{~m}$.
6 Cable extends past base by approximately $0.6^{\prime \prime}$ when carriage is at negative hard stop.

7 Cable Track extends $0.175^{\prime \prime}$ higher than carriage mounting surface. It is recommended to use optional Spacer Plate for custom mounting holes.
8 Standard cable track provided is Igus 07.30 .018 .
9 Base mounting holes are equidistant, $1.200^{\prime \prime}(12.0,16.8,21.6 \ldots .$.$) or$ $2.400^{\prime \prime}(9.6,14.4,19.2,24.0 . . .$.$) from each end depending on base length.$
10 Specification subject to change without notice.
11 Listed specifications based on motor size and typical performance requirements. Bearing manufacturer specifications exceed listed specifications. ments. Bearing manufacturer specifications exceed listed specifications.

## Dimensions shown in inches.

- Moving Carriage Assembly
- Stationary Base Assembly

|  | CARRIAGE SIZE |  |  |  |  |  |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{- 2}$ | $\mathbf{m m}$ | $\mathbf{- 3}$ | $\mathbf{m m}$ | $\mathbf{- 4}$ | $\mathbf{m m}$ |
| CL | 4.200 | 106.68 | 6.600 | 167.64 | 9.000 | 228.60 |
| A | 3.200 | 81.28 | 5.600 | 142.24 | 8.000 | 203.20 |
| B | - | 71.12 | 2.800 | 101.60 | 4.000 | 101.64 |
| COIL | $210-2$ | $210-3$ | $210-4$ |  |  |  |



| ACCURACY | STANDARD | LASER ALIGNMENT OPTION |
| :--- | :---: | :---: |
| Straightness restrained on flat surface in $[\mu \mathrm{m}]$ | $\pm 0.000127 \mathrm{in} / \mathrm{in}[ \pm 127 \mu \mathrm{~m} / \mathrm{m}]$ | $\pm .000013 \mathrm{in} / \mathrm{in}[13 \mu \mathrm{~m} / \mathrm{m}]$ |
| Flatness restrained on flat surface in $[\mu \mathrm{m}]$ | $\pm 0.003+.000254 \mathrm{in} / \mathrm{in}[ \pm 76+254 \mu \mathrm{~m} / \mathrm{m}]$ |  |
| Note: For travels less than 1 meter, Flatness should be calculated at 1 meter |  |  |
| Straightness/Flatness specifications based on system mounted to surface of flatness $\pm 0.0005 \mathrm{in} / \mathrm{tt}$ |  |  |


| PHYSICAL |  | - 2 | - 3 | - 4 | - 5 | - 6 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Carriage Assembly | lbs [kg] | 4.60 [2,1] | 6.70 [3,0] | 8.10 [3,7] | 9.50 [4,3] | 11.00 [ 5,0$]$ |
| Base Assembly |  |  |  |  |  |  |
| T3DA Aluminum (3.375 "thick) | $\mathrm{lbs} / \mathrm{ft}[\mathrm{kg} / \mathrm{m}]$ | 15.75 [23,4] |  | - | $\cdots$ | - |
| T3DB Aluminum (0.500 "thick) | $\mathrm{lbs} / \mathrm{ft}[\mathrm{kg} / \mathrm{m}]$ | 16.88 [25,1] |  |  |  | - |
| T3DS Steel (0.500 "thick) | $\mathrm{lbs} / \mathrm{ft}[\mathrm{kg} / \mathrm{m}]$ | 25.27 [37,6] | ........... |  | $\cdots$ | - |
| Carriage Length | in [mm] | 4.20 [106,7] | $6.60[167,6]$ | $9.00[228,6]$ | 11.40 [289,6] | 13.80 [350,5] |
| Coil Bar Length | in [mm] | 7.20 [182,9] | 9.60 [243,8] | 12.00 [304,8] | 14.40 [365,8] | 16.80 [426,7] |


| LOAD |  | - 2 | - 3 | - 4 | - 5 | - 6 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Vertical (Fv) see note 11 | lbs [kg] | 120 [54] | 150 [68] | 180 [81] | 210 [95] | 240 [108] |
| Side (Fs) see note 11 | lbs [kg] | 80 [36] | 100 [45] | 100 [45] | 100 [45] | 100 [45] |
| Moments-Roll (Mr) see note 11 | $\mathrm{lb}-\mathrm{ft}[\mathrm{N}-\mathrm{m}\}$ | 80 [107] | 100 [134] | 100 [134] | 100 [134] | 100 [134] |
| Moments-Pitch (Mp) see note 11 | $\mathrm{lb}-\mathrm{ft}[\mathrm{N}-\mathrm{m}\}$ | 160 [214] | 300 [402] | 300 [402] | 300 [402] | 300 [402] |
| Moments-Yaw (My) see note 11 | $\mathrm{lb}-\mathrm{ft}[\mathrm{N}-\mathrm{m}\}$ | 160 [214] | 300 [402] | 300 [402] | 300 [402] | 300 [402] |

## NOTES

1 Total travel $=0 \mathrm{AL}-3.00^{\prime \prime}(76.2 \mathrm{~mm})-$ carriage length.
2 Maximum base length is $120^{\prime \prime}(3048 \mathrm{~mm})$.
3 Aluminum base is black anodized. Steel base is nickel plated.
4 For complete motor specifications, refer to 310 series motor data sheet.
5 Renishaw encoder, RGH24 series, available in $0.05 .0 \mu \mathrm{~m}$. $0.1 \mu \mathrm{~m}, 0.5 \mu \mathrm{~m}, 1.0 \mu \mathrm{~m}, 5.0 \mu \mathrm{~m}$.
6 Cable extends past base by approximately $0.6^{\prime \prime}$ when carriage is at negative hard stop.

7 Cable Track extends 0.175 "higher than carriage mounting surface. It is recommended to use optional Spacer Plate for custom mounting holes.
8 Standard cable track provided is Igus 07.30.018.
9 Base mounting holes are equidistant, $1.200^{\prime \prime}(12.0,16.8,21.6 . .$.$) or$ $2.400^{\prime \prime}(9.6,14.4,19.2,24.0 . .$.$) from each end depending on base length.$
10 Specification subject to change without notice.
11 Listed specifications based on motor size and typical performance requirements Bearing manufacturer specifications exceed listed specifications.

## Dimensions shown in inches.

- Moving Carriage Assembly
- Stationary Base Assembly

|  | CARRIAGE SIZE |  |  |  |  |  |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{- 2}$ | $\mathbf{m m}$ | $\mathbf{- 3}$ | $\mathbf{m m}$ | $\mathbf{- 4}$ | $\mathbf{m m}$ | $\mathbf{- 5}$ | $\mathbf{m m}$ | $\mathbf{- 6}$ | $\mathbf{m m}$ |
| CL | 4.200 | $\mathbf{1 0 6 . 6 8}$ | 6.600 | 167.64 | 9.000 | 228.60 | 11.400 | 289.56 | 13.800 | 350.52 |
| A | 3.200 | 81.28 | 5.650 | 142.24 | 8.000 | 203.20 | 10.400 | 264.16 | 12.800 | 325.12 |
| B | - |  | 2.800 | 71.12 | 4.000 | 101.60 | 5.200 | 132.08 | 6.400 | 162.56 |
| COIL | $310-2$ |  | $310-3$ | $310-4$ | $310-5$ | $310-6$ |  |  |  |  |



## I-Force Ironless Motor Positioner

| PERFORMANCE |  | LINEAR MAGNETIC ENCODER5.0 <br> $1.0 .1 \mu \mathrm{~m}$ |  | $\begin{aligned} & \text { RENISHAW ENC } \\ & 0.5 \mu \mathrm{~m} \end{aligned}$ | $\begin{aligned} & \text { R OPTIONS (Note 5) } \\ & 0.1 \mathrm{~mm} \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Peak Velocity | $\mathrm{in} / \mathrm{s}[\mathrm{m} / \mathrm{s}]$ | 275 [7] | 100 [2.5] | 120 [3] | 15 [0.4] |
| Resolution | in [ $\mu \mathrm{m}$ ] | 0.0002 [5] | 0.00004 [1.0] | 0.00002 [0.5] | 0.000004 [0.1] |
| Repeatability | in [ $\mu \mathrm{m}$ ] | $\pm 0.0004[ \pm 10]$ | $\pm 0.0008$ [2.0] | $\pm 0.00006$ [1.5] | $\pm 0.00004$ [1.0] |
| Accuracy - LME |  | $\pm(30 \mu \mathrm{~m}+50 \mu \mathrm{~m} / \mathrm{m}) \quad \pm(25 \mu \mathrm{~m}+50 \mu \mathrm{~m} / \mathrm{m})$ |  |  |  |
| Accuracy - Renishaw <br> Note: For travels less than 1 meter, accuracy should be cal |  | 1 meter $\quad \pm(5 \mu \mathrm{~m}+30 \mu \mathrm{~m} / \mathrm{m})$ |  |  |  |


| MOTOR MODEL |  | $\mathbf{3 1 0 - 2}$ | $\mathbf{3 1 0 - 3}$ | $\mathbf{3 1 0 - 4}$ | $\mathbf{3 1 0 - 5}$ | $\mathbf{3 1 0 - 6}$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Peak Force | N | 409.3 | 600.0 | 790.0 | 980.0 | 1170.0 .1 |
|  | Ib | 92.0 | 135.1 | 177.2 | 220.3 | 263.2 |
| Continuous Force | N | 91.6 | 133.9 | 176.2 | 219.3 | 262.0 |
|  | Ib | 20.6 | 30.1 | 39.6 | 49.3 | 589 |
| Peak Power | W | 1885 | 2693 | 3500 | 4308 | 5116 |
| Continuous Power | W | 4 | 135 | 179 | 215 | 256 |


| ACCURACY | STANDARD | LASER ALIGNMENT OPTION |
| :--- | :---: | :---: |
| Straightness restrained on flat surface in $[\mu \mathrm{m}]$ | $\pm 0.000127[ \pm 127 \mu \mathrm{~m} / \mathrm{m}]$ | $\pm .00013 \mathrm{in} / \mathrm{in}[ \pm 13 \mu \mathrm{~m} / \mathrm{m}]$ |
| Flatness restrained on flat surface in $[\mu \mathrm{m}]$ | $\pm 0.003+.00254 \mathrm{in} / \mathrm{in}[ \pm 76+254 \mu \mathrm{~m} / \mathrm{m}]$ |  |

Note: For travels less than 1 meter, Flatness should be calculated at 1 meter
Straightness/Flatness specifications based on system mounted to surface of flatness $\pm 0.0005$ in/ft

| PHYSICAL |  | - 2 | - 3 | - 4 | - 5 | - 6 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Carriage Assembly | \|bs [kg] | 3.00 [1,4] | 4.40 [2,0] | $5.50[2,5]$ | 6.40 [2,9] | $7.40[3,3]$ |
| Base Assembly |  |  |  |  |  |  |
| T3SA Aluminum (3.375 "thick) | lbs/tt [kg/m] | 13.30 [19,8] |  | . | ....... | ........ |
| T3SB Aluminum (0.500 "thick) | $\mathrm{lbs} / \mathrm{tt}[\mathrm{kg} / \mathrm{m}]$ | 14.25 [21,2] | ......... | . | $\ldots$ | ......... |
| T3SS Steel (0.500 "thick) | lbs/tt [kg/m] | 21.24 [31,6] | ......... | ..... | - | $\cdots$ |
| Carriage Length | in [mm] | 4.20 [106,7] | 6.60 [167,6] | 9.00 [228,6] | 11.40 [289,6] | 13.80 [350,5] |
| Coil Bar Length | in [mm] | 7.20 [182,9] | 9.60 [243,8] | 12.00 [304,8] | 14.40 [365,8] | 16.80 [426,7] |


| LOAD |  | - 2 | - 3 | 4 | 5 | 6 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Vertical (Fv) see note 11 | lbs [kg] | 80 [36] | 100 [45] | 120 [54] | 140 [63] | 160 [72] |
| Side (Fs) see note 11 | lbs [kg] | 30 [13] | 50 [22] | 50 [22] | 50 [22] | 50 [22] |
| Moments-Roll (Mr) see note 11 | lb-ft [ $\mathrm{N}-\mathrm{m}$ \} | 35 [47] | 50 [67] | 50 [67] | 50 [67] | 50 [67] |
| Moments-Pitch (Mp) see note 11 | lb-ft [ $\mathrm{N}-\mathrm{m}$ \} | 75 [100] | 150 [201] | 150 [201] | 150 [201] | 150 [201] |
| Moments-Yaw (My) see note 11 | lb-ft [ $\mathrm{N}-\mathrm{m}$ \} | 75 [100] | 150 [201] | 150 [201] | 150 [201] | 150 [201] |

## NOTES

1 Total travel $=0 \mathrm{AL}-3.00^{\prime \prime}(76.2 \mathrm{~mm})-$ carriage length.
2 Maximum base length is $120^{\prime \prime}(3048 \mathrm{~mm})$.
3 Aluminum base is black anodized. Steel base is nickel plated.
4 For complete motor specifications, refer to 310 series motor data sheet.
5 Renishaw encoder, RGH24 series, available in $0.05 .0 \mu \mathrm{~m}$. $0.1 \mu \mathrm{~m}, 0.5 \mu \mathrm{~m}, 1.0 \mu \mathrm{~m}, 5.0 \mu \mathrm{~m}$.
6 Cable extends past base by approximately $0.6^{\prime \prime}$ when carriage is at negative hard stop.

7 Cable Track extends $0.175^{\prime \prime}$ higher than carriage mounting surface. It is recommended to use optional Spacer Plate for custom mounting holes.
8 Standard cable track provided is Igus 07.30.018.
9 Base mounting holes are equidistant, 1.200 " $(12.0,16.8,21.6 . .$.$) or$ $2.400^{\prime \prime}(9.6,14.4,19.2,24.0 . .$.$) from each end depending on base length.$

10 Specification subject to change without notice.
11 Listed specifications based on motor size and typical performance requirements Bearing manufacturer specifications exceed listed specifications.

## Dimensions shown in inches.

- Moving Carriage Assembly
- Stationary Base Assembly




## T4D Specifications

| PERFORMANCE |  | LINEAR MA 5.0um | IC ENCODER $1.0 .1 \mu \mathrm{~m}$ | $\begin{aligned} & \text { RENSHAW ENC( } \\ & 0.5 \mu \mathrm{~m} \end{aligned}$ | OPTIONS (Note 5) 0.1 um |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Peak Velocity | $\mathrm{in} / \mathrm{s}[\mathrm{m} / \mathrm{s}]$ | 275 [7] | 100 [2.5] | 120 [3] | 15 [0.4] |
| Resolution | in [ $\mu \mathrm{m}$ ] | 0.0002 [5] | 0.00004 [1.0] | 0.00002 [0.5] | 0.000004 [0.1] |
| Repeatability | in $[\mu \mathrm{m}]$ | $\pm 0.0004[ \pm 10]$ | $\pm 0.0008$ [2.0] | $\pm 0.00006$ [1.5] | $\pm 0.00004$ [1.0] |
| Accuracy - LME | $\pm(30 \mu \mathrm{~m}+50 \mu \mathrm{~m} / \mathrm{m}) \pm(25 \mu \mathrm{~m}+50 \mu \mathrm{~m} / \mathrm{m})$ |  |  |  |  |

Accuracy - Renishaw
$\pm(5 \mu \mathrm{~m}+30 \mu \mathrm{~m} / \mathrm{m})$
Note: For travels less than 1 meter, accuracy should be calculated at 1 meter

| MOTOR MODEL |  | 410-2 | 410-3 | 410-4 | 410-6 | 410-8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Peak Force | N | 1041.4 | 1523.6 | 2006.3 | 2967.2 | 3928.1 |
|  | lb | 234.1 | 342.5 | 451.0 | 667.0 | 883.0 |
| Continuous Force | N | 233.1 | 340.8 | 448.9 | 663.7 | 878.6 |
|  | lb | 52.4 | 76.6 | 100.9 | 149.2 | 197.5 |
| Peak Power | W | 2835 | 4050 | 5265 | 7695 | 10125 |
| Continuous Power | W | 142 | 203 | 263 | 385 | 506 |


| ACCURACY | STANDARD | LASER ALIGNMENT OPTION |
| :--- | :---: | :---: |
| Straightness restrained on flat surface in $[\mu \mathrm{m}]$ | $\pm 0.000127 \mathrm{in} / \mathrm{in}[ \pm 127 \mu \mathrm{~m} / \mathrm{m}]$ | $\pm .000013 \mathrm{in} / \mathrm{in}[ \pm 13 \mu \mathrm{~m} / \mathrm{m}]$ |
| Flatness restrained on flat surface in $[\mu \mathrm{m}]$ | $\pm .003+.000254 \mathrm{in} / \mathrm{in}[ \pm 76+254 \mu \mathrm{~m} / \mathrm{m}]$ |  |

Note: For travels less than 1 meter, Flatness should be calculated at 1 meter
Straightness/Flatness specifications based on system mounted to surface of flatness $\pm 0.0005$ in/tt

| PHYSICAL |  | - 2 | - 3 | - 4 | - 6 | - 8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Carriage Assembly |  |  |  |  |  |  |
| T4DB Aluminum | lbs [kg] | $9.0[4,1]$ | 14.9 [6,8] | 18.1 [8,2] | 24.1 [10,9] | 30.2 [13,7] |
| T4DS Steel | lbs [kg] | $13.29[6,0]$ | 22.20 [10,1] | 28.46 [12,9] | 40.51 [18,4] | 52.59 [23,9] |
| Base Assembly |  |  |  |  |  |  |
| T4DB Aluminum | $\mathrm{lbs} / \mathrm{ft}[\mathrm{kg} / \mathrm{m}]$ | 29.4 [43,8] | . | - | $\cdots$ | ......... |
| T4DS Steel | $\mathrm{lbs} / \mathrm{ft}[\mathrm{kg} / \mathrm{m}]$ | 39.3 [ 58,5$]$ | ........... | ........ | ......... | $\cdots$ |
| Carriage Length | in [mm] | 4.80 [121,9] | 8.15 [207,0] | 11.50 [292,1] | 18.20 [462,3] | 24.90 [632,5] |
| Coil Bar Length | in [mm] | 10.00 [254] | 13.36 [339] | 16.72 [424] | 23.44 [595] | 30.16 [766] |


| LOAD |  | - 2 | - 3 | - 4 | - 6 | - 8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Vertical (Fv) see note 11 | lbs [kg] | 200 [90] | 250 [113] | 300[136] | 400 [181] | 400 [181] |
| Side (Fs) see note 11 | lbs [kg] | 150 [68] | 150 [68] | 150 [68] | 150 [68] | 150 [68] |
| Moments-Roll (Mr) see note 11 | $\mathrm{lb}-\mathrm{ft}[\mathrm{N}-\mathrm{m}\}$ | 100 [133] | 150 [200] | 150 [200] | 150 [200] | 150 [200] |
| Moments-Pitch (Mp) see note 11 | $\mathrm{lb}-\mathrm{ft}[\mathrm{N}-\mathrm{m}\}$ | 200 [266] | 400 [532] | 400 [532] | 400 [532] | 400 [532] |
| Moments-Yaw (My) see note 11 | $\mathrm{lb}-\mathrm{ft}[\mathrm{N}-\mathrm{m}\}$ | 200 [266] | 400 [532] | 400 [532] | 400 [532] | 400 [532] |

## NOTES

1 Total travel = OAL - 5.50" (139.7 mm ) - carriage length.
2 Maximum base length is $120^{\prime \prime}$ (3048)
3 Aluminum base is black anodized. Steel base is nickel plated.
4 For complete motor specifications, refer to 410 series motor data sheet.
5 Renishaw encoder, RGH24 series, available in $0.05 .0 \mu \mathrm{~m}$. $0.1 \mu \mathrm{~m}, 0.5 \mu \mathrm{~m}, 1.0 \mu \mathrm{~m}, 5.0 \mu \mathrm{~m}$.
6 Cable extends past base by approximately $0.6^{\prime \prime}$ when carriage is at negative hard stop.

7 Cable Track extends 0.175 " higher than carriage mounting surface. It is recommended to use optional Spacer Plate for custom mounting holes.
8 Standard cable track provided is Igus 07.30 .028 .
9 Base mounting holes are equidistant, $1.680^{\prime \prime}(16.80,23.52 \ldots .$.$) or$ $3.360^{\prime \prime}(20.16,26.88 \ldots .$.$) from each end depending on base length.$
10 Specification subject to change without notice.
11 Listed specifications based on motor size and typical performance requirements Bearing manufacturer specifications exceed listed specifications.

## Dimensions shown in inches.

- Moving Carriage Assembly
- Stationary Base Assembly

0.281 THRU

C'BORE $0.406 \times 0.260$ DP
TOTAL TRAVEL = OAL - 5.50" (139.7) - CARRIAGE LENGTH
OAL = MULTIPLE OF 3.360" (85.34)


## I-Force Ironless Motor Positioner

## T4S Specifications

| PERFORMANCE |  | $\begin{aligned} & \text { LINEAR MAGNETIC ENCODER } \\ & \text { 5.0 } 1.0 \mathrm{um} \end{aligned}$ |  | RENISHAW ENCODER OPTIONS (Note 5)0.1 l0.1 um |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Peak Velocity | $\mathrm{in} / \mathrm{s}[\mathrm{m} / \mathrm{s}]$ | 275 [7] | 100 [2.5] | 120 [3] | 15 [0.4] |
| Resolution | in [ $\mu \mathrm{m}$ ] | 0.0002 [5] | 0.00004 [1.0] | 0.00002 [0.5] | 0.000004 [0.1] |
| Repeatability | in [ $\mu \mathrm{m}$ ] | $\pm 0.0004[ \pm 10]$ | $\pm 0.0008$ [2.0] | $\pm 0.00006[1.5]$ | $\pm 0.00004$ [1.0] |
| Accuracy - LME | $\pm(30 \mu \mathrm{~m}+50 \mu \mathrm{~m} / \mathrm{m}) \pm(25 \mu \mathrm{~m}+50 \mu \mathrm{~m} / \mathrm{m})$ |  |  |  |  |

Accuracy - Renishaw
$\pm(5 \mu \mathrm{~m}+30 \mu \mathrm{~m} / \mathrm{m})$
Note: For travels less than 1 meter, accuracy should be calculated at 1 meter

| MOTOR MODEL |  | 410-2 | 410-3 | 410-4 | 410-6 | 410-8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Peak Force | N | 1041.4 | 1523.6 | 2006.3 | 2967.2 | 3928.1 |
|  | lb | 234.1 | 342.5 | 451.0 | 667.0 | 883.0 |
| Continuous Force | N | 233.1 | 340.8 | 448.9 | 663.7 | 878.6 |
|  | lb | 52.4 | 76.6 | 100.9 | 149.2 | 197.5 |
| Peak Power | W | 2835 | 4050 | 5265 | 7695 | 10125 |
| Continuous Power | W | 142 | 203 | 263 | 385 | 506 |


| ACCURACY | STANDARD | LASER ALIGNMENT OPTION |
| :--- | :---: | :---: |
| Straightness restrained on flat surface in $[\mu \mathrm{m}]$ | $\pm 0.000125 \mathrm{in} / \mathrm{in}[ \pm 127 \mu \mathrm{~m} / \mathrm{m}]$ | $\pm 0.000013 \mathrm{in} / \mathrm{in}[ \pm 13 \mu \mathrm{~m} / \mathrm{m}]$ |
| Flatness restrained on flat surface in $[\mu \mathrm{m}]$ | $\pm 0.003+.000254 \mathrm{in} / \mathrm{in}[ \pm 76+254 \mu \mathrm{~m} / \mathrm{m}]$ |  |

Note: For travels less than 1 meter, Flatness should be calculated at 1 meter
Straightness/Flatness specifications based on system mounted to surface of flatness $\pm 0.0005 \mathrm{in} / \mathrm{ft}$

| PHYSICAL |  | - 2 | - 3 | - 4 | - 6 | - 8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Carriage Assembly |  |  |  |  |  |  |
| T4SB Aluminum | lbs [kg] | $6.5[3,0]$ | 10.3 [4,7] | 13.0 [5,9] | 17.8 [8,1] | 22.7 [10,3] |
| T4SS Steel | lbs [kg] | 8.78 [4,0] | 14.22 [6,5] | 18.47 [8,4] | 26.49 [12,0] | 34.54 [15,7] |
| Base Assembly |  |  |  |  |  |  |
| T4SB Aluminum | lbs/ft [kg/m] | 26.7 [39,8] | .......... | ....) | - | - |
| T4SS Steel | $\mathrm{lbs} / \mathrm{ft}[\mathrm{kg} / \mathrm{m}]$ | 34.9 [52,0] | ....) | . ${ }^{\text {a }}$ - | ....... | ......... |
| Carriage Length | in [mm] | 4.80 [121,9] | 8.15 [207,0] | 11.50 [292,1] | 18.20 [462,3] | 24.90 [632,5] |
| Coil Bar Length | in [mm] | 10.00 [254] | 13.36 [339] | 16.72 [424] | 23.44 [595] | 30.16 [766] |


| LOAD |  | $\mathbf{- 2}$ | $\mathbf{- 3}$ | $\mathbf{- 4}$ | $\mathbf{- 6}$ | $\mathbf{- 8}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Vertical (Fv) | see note 11 | $\mathrm{lbs}[\mathrm{kg}]$ | $150[68]$ | $175[79]$ | $175[79]$ | $200[90]$ |
| Side (Fs) | see note 11 | $\mathrm{lbs}[\mathrm{kg}]$ | $75[34]$ | $75[34]$ | $75[34]$ | $75[34]$ |
| Moments-Roll (Mr) see note 11 | $\mathrm{lb}-\mathrm{ft}[\mathrm{N}-\mathrm{m}\}$ | $50[66]$ | $100[133]$ | $100[133]$ | $100[133]$ | $100[133]$ |
| Moments-Pitch $(M \mathrm{Mp})$ see note 11 | $\mathrm{lb}-\mathrm{ft}[\mathrm{N}-\mathrm{m}\}$ | $100[133]$ | $200[266]$ | $200[266]$ | $200[266]$ | $200[266]$ |
| Moments-Yaw (My) see note 11 | $\mathrm{lb-ft}[\mathrm{~N}-\mathrm{m}\}$ | $100[133]$ | $200[266]$ | $200[266]$ | $200[266]$ | $200[266]$ |

## NOTES

[^0]7 Cable Track extends $0.175^{\prime \prime}$ higher than carriage mounting surface. It is recommended to use optional Spacer Plate for custom mounting holes.

8 Standard cable track provided is Igus 07.30 .028 .
9 Base mounting holes are equidistant, 1.680 " $(16.80,23.52 \ldots .$.$) or$ $3.360^{\prime \prime}(20.16,26.88 \ldots .$.$) from each end depending on base length.$
10 Specification subject to change without notice.
11 Listed specifications based on motor size and typical performance require Bearing manufacturer specifications exceed listed specifications.

## Dimensions shown in inches.

Moving Carriage Assembly
Stationary Base Assembly
-LIMIT
(~0.1 FROM HARD STOP) (2.54)

HOME
(~0.7 FROM HARD STOP) (17.78)

POSITIVE TRAVEL
DIRECTION DIRECTION

CARRIAGE LENGTH
-2 4.800 (121.92)
$\begin{array}{lll}-3 & 8.150 & (207.01)\end{array}$
-4 $\quad 11.500$ (292.10)
-6 18.200 (462.28)
-8 24.900 (632.46)

SHOCK
ABSORBING BUMPERS
2.750
(69.85)

TYPICAL

+ LIMIT
( 2.1 FROM HARD STOP) (2.54)
TOTAL TRAVEL = OAL - 5.50" (139.7) - CARRIAGE LENGTH
OAL = MULTIPLE OF 3.360" (985.34)


|  | CARRIAGE SIZE |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | -2 | mm | -3 | mm | -4 | mm | -6 | mm | -8 | mm |
| CL | 4.800 | 121.92 | 8.150 | 207.01 | 11.500 | 292.10 | 18.200 | 462.28 | 24.900 | 632.46 |
| A | 3.800 | 96.52 | 7.150 | 181.61 | 10.500 | 266.70 | 17.200 | 436.88 | 23.900 | 607.66 |
| B | - | - | 3.575 | 90.805 | 5.250 | 133.35 | 8.600 | 218.44 | 11.950 | 303.53 |
| COIL | 41 |  |  |  | 410 | 4 |  |  |  |  |

Order Example:


## Cable length

Cable Length
A = 1 Meter Flying Leads
B $=3$ Meter Flying Leads
C = 7.5 Meter Flying Leads
L = 3 Extension Cables
(with Connector Box)
M = 7.5 Extension Cables
(with Connector Box)
Z = Connector Box ONLY (no extension cables)
*Flying leads - cable
measured from last cable carrier link
*Extension Cables - cable
measured from
connection box at
end of base

## Encoder

$A=L M E, 1 u m$
$B=L M E$, $5 u m$
Q = Renishaw, 5 um
$\mathrm{L}=$ Renishaw, 1 um
$\mathrm{M}=$ Renishaw, 0.5 m
$\mathbf{P}=$ Renishaw, 0.1 um
$R=$ Renishaw, $1 \vee p-p$ sine/cosine
$X=$ No encoder

Order Example:


[^1]Order Example:


B = 1/2"Al

## Length of Base

XXX = Length of base In inches
Max.: 118"
Min.: 9.6"
Increment: 2.4"

* Truncate base length in part number. Example: for a 16.8 inch base, "XXX" equal "016"
Base Length $=$ Travel (increments of $2.4^{\prime \prime}$ [ 60.96 mm$]$ ) $+3.0^{\prime \prime}[76.2 \mathrm{~mm}]+$ carriage length


## Coil Size

2 = 2 pole T3S 5.0" $[127 \mathrm{~mm}]$, T3D 4.2" [106.68]
3 = 3 pole $6.6^{\prime \prime}[167.64 \mathrm{~mm}$ ]
$4=4$ pole $9.0^{\prime \prime}[228.60 \mathrm{~mm}]$
5 = 5 pole $11.4^{\prime \prime}[289.56 \mathrm{~mm}$ ]
6 = 6 pole $13.3^{\prime \prime}[350.62 \mathrm{~mm}]$


## Encoder

$A=L M E, 1 u m$
$B=L M E$, $5 u m$
$\mathbf{Q}=$ Renishaw, $5 u m$
$\mathrm{L}=$ Renishaw, 1 um
$\mathrm{M}=$ Renishaw, 0.5 m
$\mathbf{P}=$ Renishaw, 0.1 um
$\mathbf{R}=$ Renishaw, 1 V p-p sine/cosine
X = No encoder

## Cable track <br> $0=$ None 3 = Std.

## Connector

Cable Connectorization
A = Aries
B = Flying Leads
C = Compax3
G = Gemini
$\mathbf{V}=\mathrm{ViX}$
Z = no cables
*Connectorized cables only available with Connector Box

## Cable length

Cable Length
A = 1 Meter Flying Leads
B = 3 Meter Flying Leads
C = 7.5 Meter Flying Leads
L = 3 Extension Cables (with Connector Box)
M = 7.5 Extension Cables (with Connector Box)
Z = Connector Box ONLY (no extension cables)
*Flying leads - cable measured from last cable carrier link
*Extension Cables - cable measured from connection box at end of base
*7.5 Meter Flying Lead Cables available on: All bases with LME encoder All bases with Renishaw encoder under $86^{\prime \prime}$ For bases with Renishaw encoder over 86 "the cable length (CL) will be $C L=10 M-$ (base length in meters +0.3 M )

Order Example:


## Cooling <br> N no cooling

## Encoder

A = LME 1 um
$B=$ LME 5 um
5 um
M Rensaw 0.5
P Renishaw 0.1 mm
R = Renishaw IV D-p
sine/cosine
= No Encoder

Connector
Cable Connectorization
A = Aries
$\mathbf{B}=$ Flying Leads
C = Compax3
G = Gemini
V
*Connectorize cables only available with Connector Box

## Cable length

A = 1 Meter Flying Leads
B = 3 Meter Flying Leads
L = 3 Extension Cables
(with Connector Box)
= 7.5 Extension Cables (with Connector Box)
= Connector Box ONLY
*Flying leads - cable measured last cable carrier link *Extension Cables - cable at end of base
*7.5 Meter Flying Lead Cables valiable on:
All bases with LME encoder Al bases w 1e " " encoder under 86
 encoder over 86 the $\mathrm{CL}=10 \mathrm{M}-$ (base length in meters +0.3 M )

## Parker Hannifin

## The global leader in motion and control technologies and systems

## Global Partnerships Global Support

Parker is committed to helping make our customers more productive and more profitable through our global offering of motion and control products and systems. In an increasingly competitive global economy, we seek to develop customer relationships as technology partnerships. Working closely with our customers, we can ensure the best selection of technologies to suit the needs of our customers' applications.

## Electromechanical Technologies for High Dynamic Performance and Precision Motion

Parker electromechanical technologies form an important part of Parker's global motion and control offering. Electromechanical systems combine high performance speed and position control with the flexibility to adapt the systems to the rapidly changing needs of the industries we serve.

## aerospace climate control electromechanical filtration fluid \& gas handling hydraulics pneumatics process control sealing \& shielding




Parker Hannifin Corporation
With annual sales exceeding $\$ 12$ billion, Parker Hannifin is the world's leading diversified manufacturer of motion and control technologies and systems, providing precision-engineered solutions for a wide variety of commercial, mobile, industrial and aerospace markets. The company employs more than 62,000 people in 48 countries
around the world. Parker has increased its annual dividends paid to shareholders for 52 consecutive years, among the top five longest-running dividendincrease records in the S\&P 500 index. For more information, visit the company's web site at www.parker.com, or its investor information site at www.phstock.com.

# Electromechanical Automation 

Global products with local manufacturing and support

## Global Product Design

Parker Hannifin has more than 40 years' experience in the design and manufacturing of drives, controls, motors and mechanical products. With dedicated global product development teams, Parker draws on industry-leading technological leadership and experience from engineering teams in Europe, North America and Asia.

## Local Application Expertise

Parker has local engineering resources committed to adapting and applying our current products and technologies to best fit our customers' needs. Parker's engineering resources also extend to the development and manufacture of complete systems for continuous process and motion control applications.

## Manufacturing to Meet Our Customers' Needs

Parker is committed to meeting the increasing service demands that our customers require to succeed in the global industrial market. Parker's manufacturing teams seek continuous improvement through the implementation of lean manufacturing methods throughout the process. We measure ourselves on meeting our customers' expectations of quality and delivery, not just our own. In order to meet these expectations, Parker operates and continues to invest in our manufacturing facilities in Europe, North America and Asia. This allows us to minimize transportation time and cost and to be able to respond more quickly to customer needs.

## Worldwide Electromechanical Automation Manufacturing Locations

## Europe

Littlehampton, United Kingdom Dijon, France
Offenburg, Germany
Milan, Italy

## Asia

Shanghai, China
Chennai, India
North America
Charlotte, North Carolina
Rohnert Park, California
Irwin, Pennsylvania
Wadsworth, Ohio
Port Washington, New York
New Ulm, Minnesota


Offenburg, Germany


Littlehampton, UK

# Local Manufacturing and Support in Europe 

Parker provides sales assistance and local technical support through a group of dedicated sales teams and a network of authorized technical
distributors throughout Europe. For contact information, please refer to the Sales Offices on the back cover of this document or visit www.parker.com.


Milan, Italy


Dijon, France

# Solutions to Improve Productivity, Increase Flexibility and Save Energy 

## Process Productivity and Reliability

Parker brings together the technology and experience required for continuous process applications across many industries. AC and DC variable speed drive products combined with application-specific function block-based configuration software ensure precise speed control and reliable performance. Parker combines more than 30 years of application experience with a global sales and support network that help you increase your machine availability.


Converting machinery

| Folding, gluing, stitching and collating | $\checkmark$ | $\checkmark$ |  | $\checkmark$ |
| :--- | :---: | :---: | :---: | :---: |
| Coating, laminating and foil stamping | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| Slitting, cutting and rewinding | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |

Plastics processing machinery

| Plastic extrusion | $\checkmark$ |  | $\checkmark$ |  |
| :--- | :---: | :---: | :---: | :---: |
| Injection moulding | $\checkmark$ |  | $\checkmark$ | $\checkmark$ |
| Thermal forming | $\checkmark$ |  | $\checkmark$ | $\checkmark$ |

Wire and cable

| Wire and cable manufacturing | $\checkmark$ | $\checkmark$ |  | $\checkmark$ |
| :--- | :---: | :---: | :---: | :---: |
| Winding/unwinding | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| Extrusion for wire and cable | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |

## Printing Machinery

| Web/sheetfed offset | $\checkmark$ |  | $\checkmark$ | $\checkmark$ |
| :--- | :---: | :---: | :---: | :---: |
| Flexo printing | $\checkmark$ |  | $\checkmark$ | $\checkmark$ |
| Gravure printing | $\checkmark$ |  | $\checkmark$ | $\checkmark$ |
| Shaftless printing | $\checkmark$ |  | $\checkmark$ | $\checkmark$ |

Other industries

| Paper machinery | $\checkmark$ |  | $\checkmark$ |  |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Sugar processing | $\checkmark$ | $\checkmark$ |  |  |
| Steel production | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| Construction materials | $\checkmark$ | $\checkmark$ |  |  |
| Automotive test rigs | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |

## Energy Efficiency and Clean Power

Parker has developed the technology to maximize the efficient use of energy in industrial, mobile and infrastructure environments.
Hybrid Vehicle Technology
Parker has adapted its electric drive technologies for use in hybrid electric vehicles, including utility vehicles and passenger vehicles. Examples include inverters and motor drives, as well as electric drive motors.

## Energy Savings for Pumps, Fans and Compressors

Parker has the drive technology to help you make significant energy savings in the operation of pumps, fans and compressors in both industrial and infrastructure applications, including:

- Commercial refrigeration
- Water and wastewater treatment
- Building automation
- Industrial processes
- Hydraulic systems



## Power Generation and Conversion

Using proven inverter technology, Parker has developed numerous solutions for the conversion of energy for commercial use from a variety of sources, including wind, wave and energy storage devices.

## Motion Control Systems for Total Production Flexibility

Parker's electromechanical automation customers enjoy total production flexibility in their general and precision motion control applications. Complete packaged linear positioning systems, coupled to servo and stepper drives and controls, enable our customers to develop a complete motion solution with one partner. Parker provides the products for a wide range of motion needs- power, speed, travel, forcewith easy to use controls designed to work on multiple control and communication platforms. Additionally, Parker's products can be easily customized to suit specific applications.


| Assembly machinery |  |  | $\stackrel{\mathbb{B}}{\stackrel{\otimes}{\partial}}$ | $\begin{aligned} & \infty \\ & \hline \text { O } \\ & 0.0 \\ & 0 \end{aligned}$ | $\overline{\text { i }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Pick and place | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| Lifting | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| Transfer machinery | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |

## Automotive assembly

| Resistance welding | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Painting applications | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| Transfer machinery | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |

Packaging machinery

| Primary, secondary, tertiary | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Handling machinery | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |

Food processing machinery

| Processing machinery | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Packaging machinery | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| Handling machinery | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |

Material handling systems

| Transfer systems | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Pick and place systems | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |

Metal forming machinery

| Presses | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Tube bending | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| Handling applications | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |

## Machine tools

| Spindles | $\checkmark$ | $\checkmark$ |
| :---: | :---: | :---: |
| Ancillary axes | $\checkmark$ | $\checkmark$ |

Semiconductor machinery

| Front end processes | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Inspection machinery | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| Packaging machinery | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| Lithography | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |

Medical devices

| Device manufacturing | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Product packaging and dispensing | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| Scanning equipment | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |  |
| Pumps and analyzers |  | $\checkmark$ | $\checkmark$ |  |  |

## Entertainment

Theatre and studio automation
Simulation and amusement rides


## Complete Range of Solutions




## Value Added Services

In addition to providing products and systems, Parker also provides a number of value added services to our customers:

- Programming and commissioning services
- Power quality and energy surveys
- 24-hour support and service
- Product repairs
- Product training


## Customization

Many automation applications cannot be solved with off the shelf products. Parker's products are designed to be versatile as well as easy to configure for the majority of industrial and process applications. Some customers require solutions that can't be found in a catalogue, and Parker has the resources and expertise available to provide customized solutions:

- Custom motor designs
- Customized mechanical positioning systems
- Customized control functionality
- Customized communication solutions




## System Solutions

Parker offers system design and manufacturing in two main categories:

## Drive Systems

Complete AC and DC drive systems across a wide power range, from less than 1 kW to more than 1 MW . Systems typically include electrical enclosure, ancillary electronic equipment and full documentation. Commissioning and support services are standard.

## Mechanical Systems

Parker has more than 20 years of experience in providing a variety of multiple axis mechanical positioning systems, complete with motors, drives and controls. Typical applications include material transfer and pick and place gantry systems. Additionally, Parker designs and builds custom precision positioning systems, integrating precision bearing, feedback and drive systems, including Parker's range of linear servo motors. Each system ships complete with motors, drives and controls, and can include the programming and commissioning.

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[^0]:    1 Total travel = OAL - 5.50" $(139.7 \mathrm{~mm})$ - carriage length.
    2 Maximum base length is $168^{\prime \prime}, 4.2$ meters.
    3 Aluminum base is black anodized. Steel base is nickel plated.
    4 For complete motor specifications, refer to 410 series motor data sheet.
    5 Renishaw encoder, RGH24 series, available in $0.05 \mu \mathrm{~m}, 0.1 \mu \mathrm{~m}, 0.5 \mu \mathrm{~m}$, $1.0 \mu \mathrm{~m}, 5.0 \mu \mathrm{~m}$.
    6 Cable extends past base by approximately $0.6^{\prime \prime}$ when carriage is at negative hard stop.

[^1]:    *Consult factory for longer lengths.

